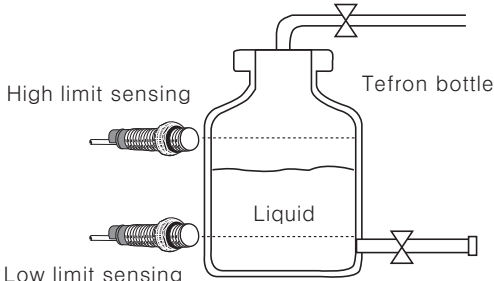
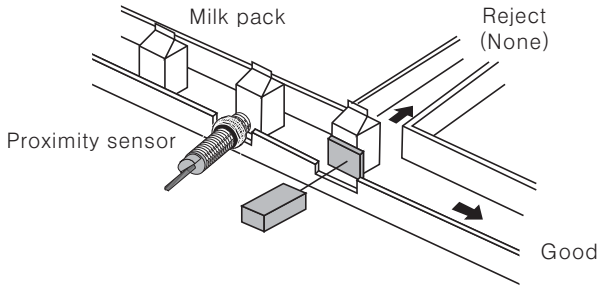
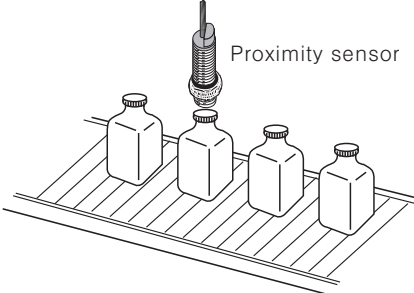
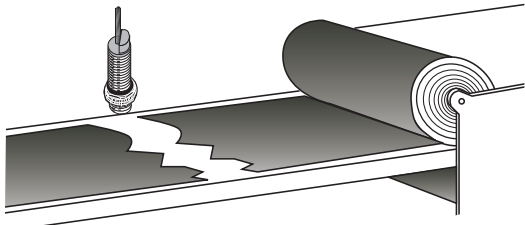
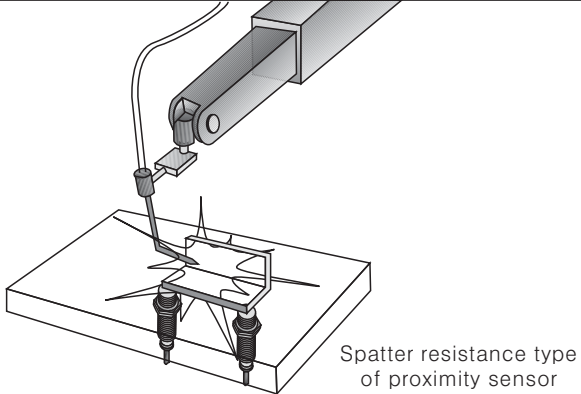
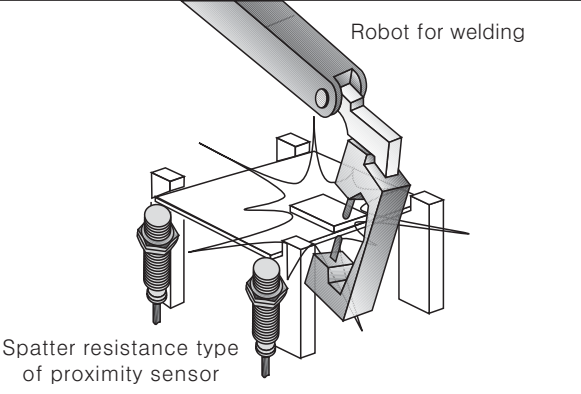
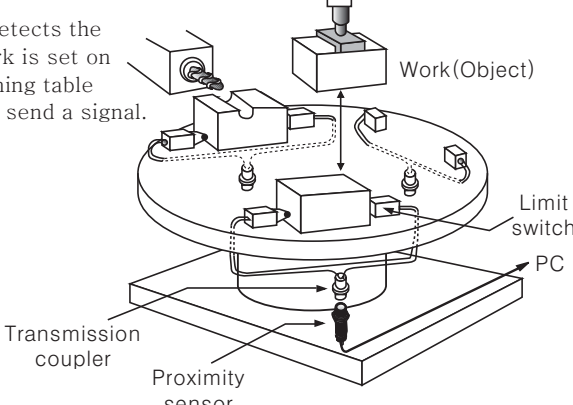
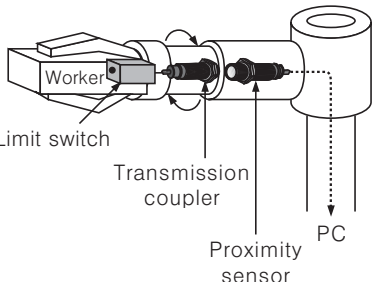


■ Applications

<p>Sensing of liquid level(Capacitive type)</p> <p>It is able to detect the level of liquid inside of bottle from outside.</p>  <p>High limit sensing</p> <p>Tefron bottle</p> <p>Liquid</p> <p>Low limit sensing</p>	<p>Sensing milk in paper pack(Capacitive type)</p> <p>It is able to detect milk in side of pack by capacitive proximity sensor.</p>  <p>Milk pack</p> <p>Proximity sensor</p> <p>Reject (None)</p> <p>Good</p>
<p>Sensing of cap of bottles(Capacitive type)</p>  <p>Proximity sensor</p>	<p>Sensing of band defective(Capacitive type)</p>  <p>Proximity sensor</p>
<p>Fixing the point to be welded(Arc)</p>  <p>Spatter resistance type of proximity sensor</p>	<p>Checking the position for Spot welding</p>  <p>Robot for welding</p> <p>Spatter resistance type of proximity sensor</p>
<p>Turning table(Transmission coupler)</p> <p>It detects the work is set on turning table and send a signal.</p>  <p>Work(Object)</p> <p>Limit switch</p> <p>PC</p> <p>Transmission coupler</p> <p>Proximity sensor</p>	<p>Transmitting the signal of checking(Transmission coupler)</p> <p>It detects if the robot arm is holding the work and send a signal.</p>  <p>Worker</p> <p>Limit switch</p> <p>Transmission coupler</p> <p>Proximity sensor</p> <p>PC</p>

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/Socket

(H) Temp. controller

(I) SSR/Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/Speed/Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching power supply

(Q) Stepping motor & Driver & Controller

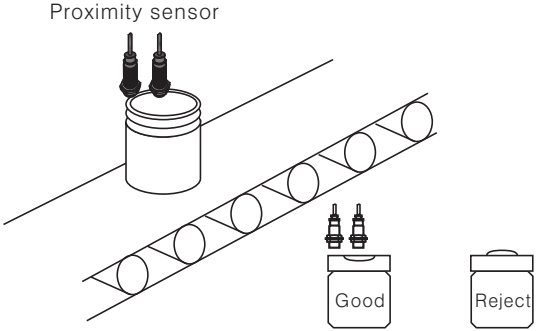
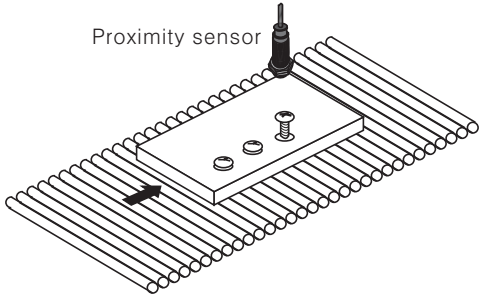
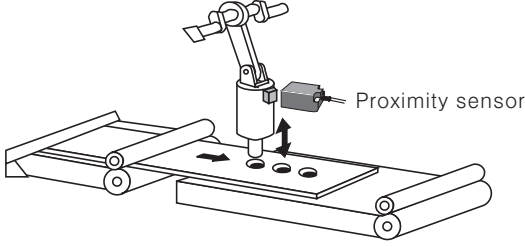
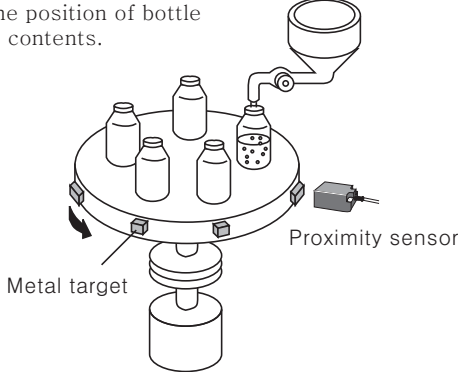
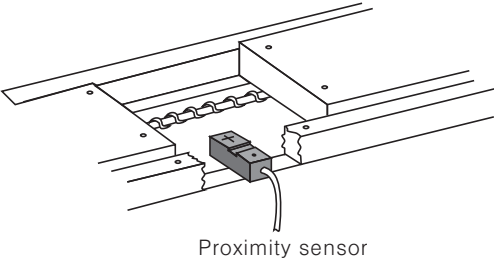
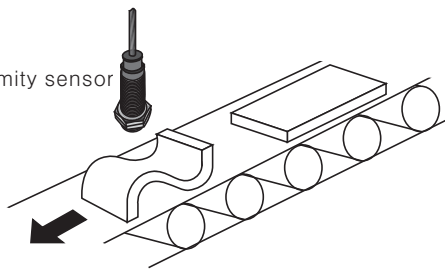
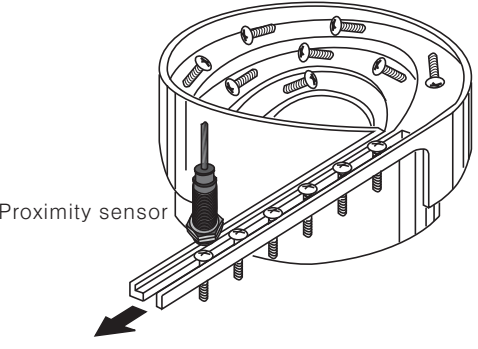
(R) Graphic/Logic panel

(S) Field network device

(T) Production stoppage models & replacement

Applications

■ Applications

<p>Sensing condition of cans</p> 	<p>Measuring the height of screw</p> <p>Sensing the status of screw</p> 
<p>Controlling a press</p> <p>Making a hole on panel by constant distance</p> 	<p>Positioning control</p> <p>Sensing the position of bottle for fill the contents.</p> 
<p>Sensing position of target</p> <p>Automatic assembly conveyor line</p> 	<p>Sensing incorrect shape of target</p> 
<p>Counting screws</p> 	<p>Sensing position of target(PFI 25)</p> <p>Automatic assembly conveyor line</p> 