# **ODATALOGIC**

## **SG BODY REFLECTOR MUTING**



**Instruction Manual** 

#### **ODATALOGIC**

#### ORIGINAL INSTRUCTIONS (ref. 2006/42/EC)

This product is covered by one or more of the following patents. Italian Patent IT 1,363,719

Additional patents pending

Datalogic Automation S.r.l. Via Lavino, 265 40050 - Monte S. Pietro Bologna - Italy

SG BODY REFLECTOR MUTING Instruction Manual

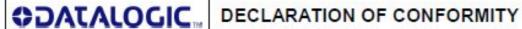
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Datalogic Automation S.r.l.

Via Lavino 265 40050 Monte San Pietro Bologna - Italy www.automation.datalogic.com

declares that the

SG4; SAFETY LIGHT CURTAINS - ELECTRO-SENSITIVE PROTECTIVE EQUIPMENT (TYPE 4 ESPE)

and all its models

are in conformity with the requirements of the European Council Directives listed below:

2006 / 42 / EC Machinery Directive 2004 / 108 / EC EMC Directive 2006 / 95 / EC Low Voltage Directive

This Declaration is based upon compliance of the products to the following standards:

SAFETY OF MACHINERY - ELECTRO-SENSITIVE PROTECTIVE EQUIPMENT. EN 61496-1: 2004

PART 1: GENERAL REQUIREMENTS AN TESTS

IEC 61496-2: 2006 SAFETY OF MACHINERY - ELECTRO-SENSITIVE PROTECTIVE EQUIPMENT. PART 2:

PARTICULAR REQUIREMENTS FOR EQUIPMENT USING ACTIVE OPTO-ELECTRONIC

PROTECTIVE DEVICES (AOPDs)

IEC 61508-1/3/4: 1998 FUNCTIONAL SAFETY OF ELECTRICAL/ELECTRONIC/PROGRAMMABLE ELECTRONIC

SAFETY-RELATED SYSTEMS. IEC 61508-2:2000

SAFETY OF MACHINERY -- SAFETY-RELATED PARTS OF CONTROL SYSTEMS EN 954-1: 1996 SAFETY OF MACHINERY -- SAFETY-RELATED PARTS OF CONTROL SYSTEMS --EN ISO 13849-1: 2008

PART 1: GENERAL PRINCIPLES FOR DESIGN

SAFETY OF MACHINERY - FUNCTIONAL SAFETY OF SAFETY-RELATED ELECTRICAL, EN 62061: 2005

ELECTRONIC AND PROGRAMMABLE ELECTRONIC CONTROL SYSTEMS

EN 50178:1997 ELECTRONIC EQUIPMENT FOR USE IN POWER INSTALLATIONS

EN 61000-6-2: 2005 ELECTROMAGNETIC COMPATIBILITY (EMC)

PART 6-2: GENERIC STANDARDS - IMMUNITY FOR INDUSTRIAL ENVIRONMENTS

EN 55022 (CLASS A ITE): 2010 LIMITS AND METHODS OF MEASUREMENTS OF RADIO DISTURBANCE OF INFORMATION

TECHNOLOGY EQUIPMENT

Conformity has been certified by the following Notified/Competent Body (identification n°0123): TÜV S ÜD Rail GmbH, Ridlerstrasse, 65 - D80339 München

Datalogic Automation have a quality system certified by the CSQ, Nr. 9115.IES2, as per ISO 9001 and have therefore observed the regulations foreseen during development and production

Monte San Pietro, January 20th 2012

Paolo Morselli Quality Manager











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#### 1. GENERAL INFORMATIONS ABOUT THIS DOCUMENT

Read this section carefully before implementing the instructions given in this manual and starting up the SG BODY safety system.

#### 1.1. Purpose of this document

These instructions for use are addressed to the manufacturer technicians or staff operating the machine and give all necessary instructions for correct and safe assembly, setup, electric connection and commissioning of the SG BODY series light curtains.

Scope of this document excludes information about use of the machine the safety system is installed to

#### 1.2. Intended readers

The instructions for use given herein are addressed to designers, manufacturers and persons in charge of the safety of systems to be equipped with the SG BODY series light curtains. They are also addressed to the staff in charge of installing the SG BODY light curtain to a machine, commissioning it or servicing it.

#### 1.3. Informations for the use

These instructions for use contain the following details about the SG BODY series light curtains:

- installation	- diagnostics and troubleshooting
- electrical connection	- user interface warnings
- commissioning and setup	- conformity and type approval
- application	- care and maintenance

Designing and using safety devices to integrate to the SG BODY safety system requires specific know-how which is not included in this document. In particular, the applicable industry standards shall be met.

General information about accident-prevention protection by means of optoelectronic safety devices can be found in the "Safety guide" available on the product CD-Rom provided with the product.

For all the acronyms used in this document please refer to section 14.10.

#### 2. GENERAL INFORMATIONS ABOUT THE PRODUCT

#### 2.1. General description of the safety light curtains

The safety light curtains of the SG BODY series are optoelectronic multibeam devices that are used to protect working areas that, in presence of machines, robots, and automatic systems in general, can become dangerous for operators that can get in touch, even accidentally, with moving parts.

The light curtains of the SG BODY series are safety systems used as accident-prevention protection devices and are manufactured in accordance with the international Standards in force for safety, in particular:

CEI IEC 61496-1: 2004 Safety of machinery: electro-sensitive protective equipment.

Part 1: General prescriptions and tests.

**CEI IEC 61496-2:** 2006 Safety of machinery: electro-sensitive protective equipment.

Particular requirements for equipment using active optoelectronic protective

devices.

The device, consisting in one active unit inside a sturdy aluminium profile and a passive unit composed of two or more deviating mirrors, generates couples of infrared beams able to detect an opaque object positioned within the light curtain detection field.

The active unit is composed of two types of optic groups: emitting and receiving units. The infrared beam, generated by an emitting optic group, is reflected by the deviating mirrors and thus re-guided towards the corresponding receiving optic group of the active unit.

The passive unit is composed of a sturdy aluminium profile containing pre-assembled and pre-aligned mirrors.

The solution with integrated Muting arms can be implemented both in a 'T' or 'L' configuration.

The active unit is equipped with the command and control functions. The connections are made through a M12 connector located in the lower side of the profile of the active unit.

The microprocessor guarantees the check and the management of the beams that are sent and received through the units: The microprocessor LEDs and display inform the operator about the general conditions of the safety light curtain (see section 8 "DIAGNOSTICS").

The device consists in 2 units: the active unit and the passive unit. The active unit, according to the model, is composed by one or several emitting and receiving modules and checks the control operations and safety actions.

During installation, an user interface facilitates the alignment of both units (see section 7 – "ALIGNMENT PROCEDURE").

As soon as an object or the operator's body accidentally interrupts one or some of the infrared beams sent by the emitter, the receiver immediately opens the OSSD outputs and blocks the MPCE machine (if correctly connected to the OSSD).

Some parts or sections of this manual containing important information for the user or installing operator are preceded by a note:



Notes and detailed descriptions about particular characteristics of the safety devices in order to better explain their functioning.

Special instructions regarding the installation process.



The information provided in the paragraphs following this symbol is very important for safety and may prevent accidents.

Always read this information accurately and carefully follow the advice to the letter.

This manual contains all the information necessary for the selection and operation of the safety devices.

However, specialised knowledge not included in this technical description is required for the planning and implementation of a safety light curtain on a power-driven machine. As the required knowledge may not be completely included in this manual, we suggest the customer to contact DATALOGIC AUTOMATION Technical Service for any necessary information relative to the functioning of the SG BODY light curtains and the safety rules that regulate the correct installation (see section 9 – "PERIODICAL MAINTENANCE AND WARRANTY").

#### 2.2. Appearance and interface

#### 2.2.1. Package contents

Package contains the following objects:

- Active unit
- SG BODY quick installation guide
- SG BODY CD containing instruction manual and other documents
- Checklist and periodical maintenance schedule

#### 2.3. Main functions and new features

With respect to SE4-R series, the SG BODY safety light curtain series present new important features:

- No dead zone
- New engineering of passive unit
- Shorter response time (see section 11 "TECHNICAL DATA")
- Muting function customization
- Override function customization

#### 2.4. How to choose the device

The SG BODY series light curtains efficiently satisfy all applications that require the Muting function thanks to pre-assembled, pre-cabled and pre-aligned Muting sensors.

T-shaped models are available with integrated Muting sensors for bidirectional Muting, L-shaped models for unidirectional Muting and linear models without integrated Muting sensors are available.

By means of Muting arms accessories, linear models can be converted into T-shaped models and L-shaped models.

The muting arms, available in "T" and "L" versions, take advantage of retroretroreflex sensors technology. This version covers a maximum operating distance of light curtain of 3 m.

The integrated Muting solution with "L" configuration facilitates sensor installation and suits applications requiring one-way object passage direction.

The integrated Muting solution with "T" configuration facilitates sensor installation and is ideal for applications requiring a bidirectional object passage movement.

The linear models, presenting a specific connector allowing easy connection of the Muting sensors, is recommended for difficult or particular applications.

Sensor positioning has to be carried out by the operator, respecting the precautions listed in the following chapters.

There are at least three different main characteristics that should be considered when choosing a safety light curtain, after having evaluated the risk assessment:

#### 2.4.1. Resolution

The resolution of the device is the minimum dimension that an opaque object must have in order to obscure at least one of the beams that constitute the sensitive area.

The resolution strictly depends on the part of the body to be protected.

The following table shows the values of the optic interaxis ( $\mathbf{I}$ ), the resolution ( $\mathbf{R}$ ) and the optic diameter ( $\mathbf{d}$ ), of the safety light curtains.

Model	Optic interaxis (/) [mm]	N. optics	Resolution ( <i>R</i> ) [mm]	Lens diameter ( <i>d</i> ) [mm]	ESPE Type
SG4-RB2-050-OO-W SG4-RB2L-050-OO-W SG4-RB2T-050-OO-W	500	2	519,75	19,75	Body protection  Type 4
SG4-RB3-080-OO-W SG4-RB3L-080-OO-W SG4-RB3T-080-OO-W	380	3	399,75	19,75	Body protection  Type 4
SG4-RB4-090-OO-W	300	4	319,75	19,75	Body protection  Type 4
SG4-RB4-120-OO-W	400	4	419,75	19,75	Body protection  Type 4

As shown in Figure 1, the resolution depends only on the geometrical characteristics of the lenses, diameter and distance between centres, and is independent from any environmental and operating conditions of the safety light curtain.

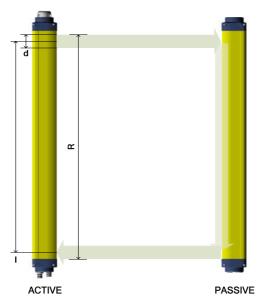


Figure 1

The resolution value is obtained applying the following formula: R = I + d

#### where:

*I* = Distance between two adjacent optics

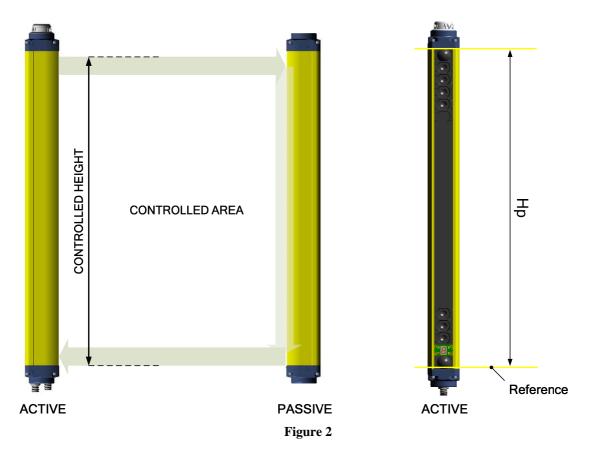
d= Lens diameter

Note: Safety light curtains for body protection with sensitive area heights and optic interaxis different from the standard versions can be manufactured upon specific request.

#### 2.4.2. Controlled height

The controlled height is the height protected by the safety light curtain (Hp). SG BODY models have no dead zone inside the protected area.

In Figure 2, Figure 3 and Figure 4 SG BODY Reflector schemes respectively for 2 beams, 3 beams and 4 beams models are shown.



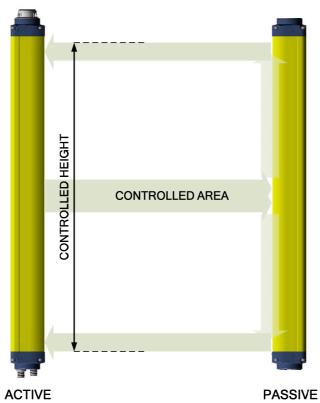


Figure 3

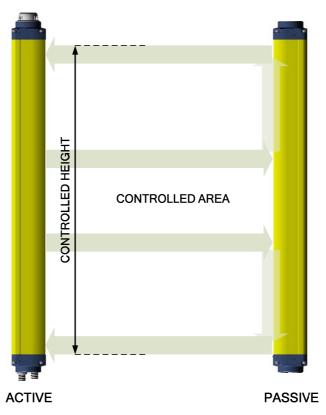


Figure 4

Model	Hp [mm]	ESPE Type
SG4-RB2-050-OO-W SG4-RB2L-050-OO-W SG4-RB2T-050-OO-W	500	Body protection  Type 4
SG4-RB3-080-OO-W SG4-RB3L-080-OO-W SG4-RB3T-080-OO-W	800	Body protection  Type 4
SG4-RB4-090-OO-W	900	Body protection  Type 4
SG4-RB4-120-OO-W	1200	Body protection  Type 4

#### 2.4.3. Minimum installation distance

As shown in Figure 5, the safety device must be positioned at a specific safety distance. This distance must ensure that the dangerous area cannot be reached before the dangerous motion of the machine has been stopped by the ESPE.

The safety distance depends on 4 factors, according to the **EN-999** "Safety of machinery - The positioning of protective equipment in respect of approach speeds of parts of the human body" Standard:

- Response time of the ESPE (the time between the effective beam interruption and the opening of the OSSD contacts).
- Machine stopping time (the time between the effective opening of the contacts of the ESPE and the real stop of the dangerous motion of the machine).
- ESPE resolution.
- Approaching speed of the object to be detected.

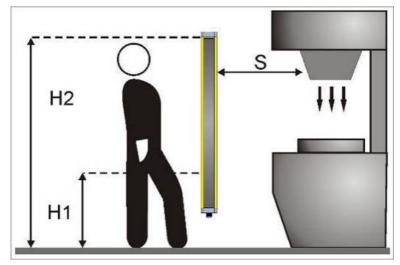


Figure 5

The following formula is used for the calculation of the safety distance:

$$S = K (t_1 + t_2) + C$$

#### where:

S = Minimum safety distance in mm.

K = Speed of the object, limb or body approaching the dangerous area in mm/sec.

t<sub>1</sub> = Response time of the ESPE in seconds (see section 11 – "TECHNICAL DATA")

t<sub>2</sub> = Machine stopping time in seconds.

d = Resolution of the system.

C = Additional distance based on the possibility to insert the body or one of body parts inside the dangerous area before the protective device trips.

C = 8 (d - 14) for devices with resolution  $\leq 40$ mm

C = 850 mm for devices with resolution > 40mm



NOTE: K value is:

2000 mm/s if the calculated value of S is  $\leq$  500 mm 1600 mm/s if the calculated value of S is > 500 mm

When devices with > 40 mm resolution are used, the height of the top beam has to be  $\geq$  900 mm (H2) from machine supporting base while the height of the bottom beam has to be  $\leq$  300 mm (H1). If the safety light curtain must be mounted in a horizontal position (Figure 6), the distance between the dangerous area and the most distant optical beam must be equal to the value calculated using the following formula:

$$S = 1600 \text{ mm/s} (t_1 + t_2) + 1200 - 0.4 \text{ H}$$

#### where:

S = Minimum safety distance in mm.

t<sub>1</sub> = Response time of the ESPE in seconds (see section 11 – "TECHNICAL DATA")

t<sub>2</sub> = Machine stopping time in seconds.

H = Beam height from ground. This height must always be less than 1000 mm.

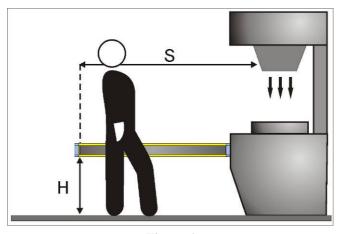


Figure 6

#### **Practical examples**

Let's suppose to have a light curtain with height = 500 mm

To calculate the distance of the device from the ESPE, in a <u>vertical position</u>, the following formula is used:

$$S = K*T + C$$

#### where:

 $T = t_1 + t_2$ 

t<sub>1</sub> = ESPE response time + SE-SR2 relay release time (max 80 ms)

 $t_2$  = Machine total stopping time (e.g. 300 ms).

C = 8 (d-14) for devices with resolution  $\leq 40$ mm

C = 850 mm for devices with resolution > 40mm

d = resolution

In all cases, if K = 2000mm/sec then S > 500 mm. Distance will have then to be recalculated using K = 1600 mm/sec.

	SGx-RB2	SGx-RB4
T [sec]	0.391	0.392
C [mm]	850	850
S [mm]	1475.6	1477.2

x = ESPE Type: 2,4



<u>WARNING:</u> The reference standard is *EN 999 "Machine safety - the positioning of the protective device based on the approaching speed of the human body"*. The following information is to be considered as indicative and concise. For correct safety distance please refer to complete standard EN-999.

#### 2.5. Typical applications

The **SAFE**asy<sup>TM</sup> safety light curtains of the SG BODY Series are used in all automation fields where control and protection of the access to dangerous zones is necessary, as well as allowing, by means of the Muting function, material passage inside a dangerous zone during working. In particular they are used to stop the moving mechanical parts in:

- Access control
- Working areas
- Packaging machines, handling machines, storing machines;
- Automatic and semi-automatic assembly lines;
- Automatic warehouses;
- Robotics.

In food industry applications, Datalogic Automation Technical Service has to verify the compatibility of the material of the safety light curtain housing with any chemical agents used in the production process.

The following pictures show some main applications.

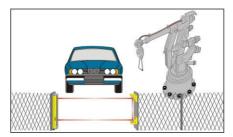


Figure 7 - Robotised assembly lines

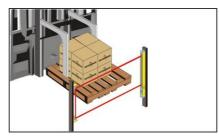


Figure 8 - Transfer areas

#### 2.6. Safety information



For a correct and safe use of the safety light curtains of the SG BODY series, the following points must be observed:

- The stopping system of the machine must be electrically controlled.
- This control system must be able to stop the dangerous movement of the machine within the total machine stopping time T as per paragraph 2.4.3, and during all working cycle phases.
- Mounting and connection of the safety light curtain must be carried out by qualified personnel only, according to the indications included in the special sections (refer to sections 3, 4, 5, 7) and to the applicable standards.

- The safety light curtain must be securely placed in a particular position so that access to the dangerous zone is not possible without the interruption of the beams (refer section 3 "INSTALLATION MODE").
- The personnel operating in the dangerous area must be well trained and must have adequate knowledge of all the operating procedures of the safety light curtain.
- The TEST button must be located outside the protected area because the operator must check the protected area during all the Test operation.
- The RESET/RESTART button must be located outside the protected area because the operator must check the protected area during all the Reset/Restart operations.
- The OVERRIDE buttons must be located outside the protected area because the operator must check the protected area during all the Override operations.
- The external signalling lamp of the active Muting/Override must be visible from all operating sides.
- Please carefully respect the mounting instructions for the correct functioning of the Muting devices.
- The function of the external device monitoring (EDM) is active only if the specific wire is correctly connected to the device. Please carefully read the instructions for the correct functioning before powering the light curtain.
- Please carefully read the instructions for the correct functioning before powering the light curtain.

#### 3. INSTALLATION MODE

#### 3.1. Precautions to be observed for the choice and installation of the device



Make sure that the protection level assured by the SG BODY series device (Type 2 or Type 4 respectively) is compatible with the real danger level of the machine to be controlled, according to EN 954-1 and EN13849-1.

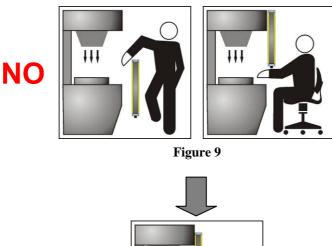
- The outputs (OSSD) of the ESPE must be used as machine stopping devices and not as command devices (the machine must have its own START command).
- The dimension of the smallest object to be detected must be larger than the resolution level of the device.
- The ESPE must be installed in a room complying with the technical characteristics indicated in section 11 TECHNICAL DATA. Datalogic Automation does not recommend the use of the product in ambients where direct or indirect exposure to solar light is present.
- Do not install device near strong and/or flashing light sources or close to similar devices.
- Strong electromagnetic disturbance might negatively affect device operation. Should this be the case contact DATALOGIC Technical Service.
- The operating distance of the device can be reduced in presence of smog, fog or airborne dust.
- A sudden change in environment temperature, with very low minimum peaks, can generate a small condensation layer on the lenses and so jeopardise functioning.
- The Muting/Override function is signalled by a specific Muting/Override signalling lamp. Ensure that the signalling device has sufficient lighting and visibly positioned near the dangerous zone.
- Ensure to correctly use Muting sensors as described in the instructions supplied hereinafter. Avoid incongruent connections that cannot be controlled and thus excluding undesired potentially dangerous activations.

#### 3.2. General information on device positioning

Pay special care when positioning the safety light curtain so to offer effective protection. The device should be installed in such a way that the dangerous area can only be entered after detecting the sensitive area.



Figure 9 shows some examples of possible access to the machine from the top and the bottom sides. These situations may be very dangerous and so the installation of the safety light curtain at sufficient height in order to completely cover the access to the dangerous area becomes necessary (see Figure 10).



YES



Figure 10

Under standard operating conditions, machine starting must not be possible while operators are inside the dangerous area.

When the installation of the safety light curtain very near to the dangerous area is not possible, a second light curtain must be mounted in a horizontal position in order to prevent any lateral access, as shown in **Errore. L'origine riferimento non è stata trovata.**.



If the operator is able to enter the dangerous area, an additional mechanical protection must be mounted to prevent the access.

YES



Figure 11



Figure 12

#### 3.2.1. Minimum installation distance

Refer to paragraph 2.4.3 - Minimum installation distance.

#### 3.2.2. Minimum distance from reflecting surfaces

Reflecting surfaces placed near the light beams of the safety device (over, under or laterally) can cause passive reflections. These reflections can affect the recognition of an object inside the controlled area.

However, if the RX receiver detects a secondary beam (reflected by the side-reflecting surface) the object might not be detected, even if the object interrupts the main beam.

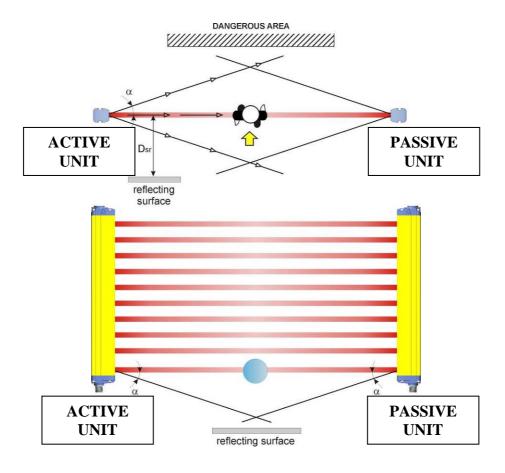


Figure 13

It is thus important to position the safety light curtain according to the minimum distance from reflecting surfaces.

The minimum distance depends on:

- operating distance between active and passive units.
- real aperture angle of ESPE (EAA); especially:

for ESPE type 4 EAA<sub>MAX</sub> = 
$$5^{\circ}$$
 ( $\alpha = \pm 2.5^{\circ}$ )

Diagram of Figure 14 shows the minimum distance from the reflecting surface  $(D_{sr})$ , based on the operating distance for a Type 4 ESPE:

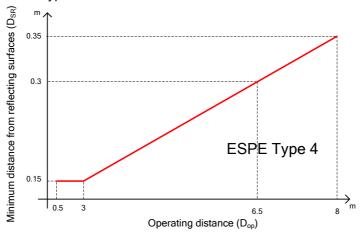


Figure 14

The formula to get D<sub>sr</sub> for a Type 4 ESPE is the following:

$$D_{sr}(m) = 0.15$$
 for operating distance < 3 m  $D_{sr}(m) = 0.5$  x operating distance (m) x tg  $2\alpha$  for operating distance  $\geq 3$  m

Even in presence of beam interruption due to reflecting objects, the correct device functioning is guaranteed and certified up to a maximum operating distance of 6.5m for SG4-RB4-090 model, or 8 m for SG4-RB2-050, SG4-RB3-080, SG4-RB4-120 models. The use of the device at higher distances, when possible, is however not recommended. If used, the user must check the correct functioning verifying that no dangerous reflections towards the receiving optics are generated by shiny objects (Figure 15).

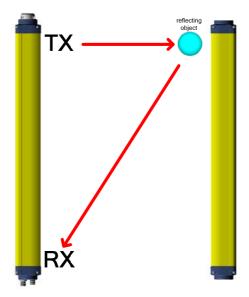


Figure 15

#### 3.2.3. Distance between homologous devices

If different safety devices have to be installed in adjacent areas, the emitter of one device must not interfere dangerously with the receiver of the other device.

Passive B interfering device must be positioned outside a minimum  $D_{do}$  distance from the active – passive axis of the device A.

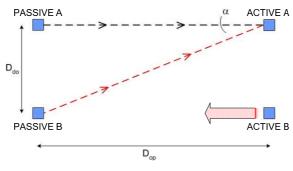


Figure 16

This minimum D<sub>do</sub> distance depends on:

- the operating distance between Passive A and Active A;
- the effective aperture angle of the ESPE (EAA); especially:

for ESPE type 4 EAA<sub>MAX</sub> = 
$$5^{\circ}$$
 ( $\alpha = \pm 2.5^{\circ}$ )

<u>WARNING:</u> the interfering device Passive B must be positioned at the same  $D_{do}$  distance, calculated as shown above, even if closer to Passive A respect to Active A.

The following graphic shows the distance from the interfering devices ( $D_{do}$ ) according to the operating distance ( $D_{oo}$ ) of the couple Passive A – Active A for a Type 4 ESPE.

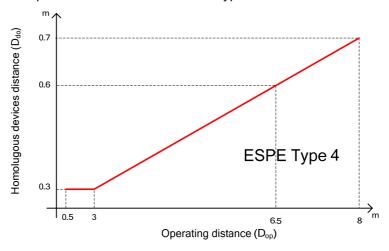


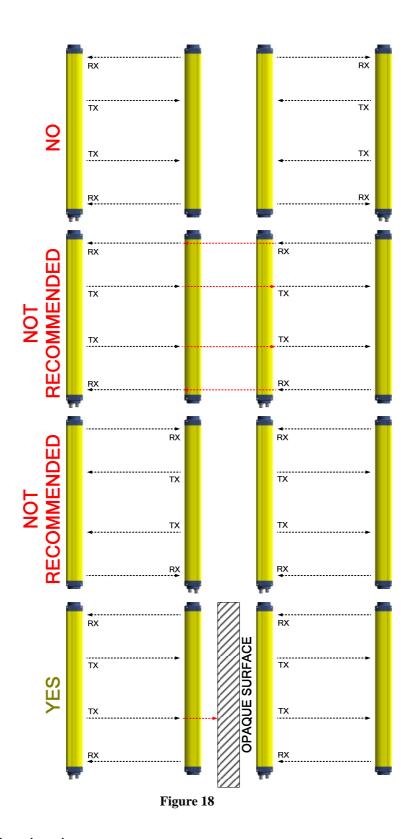
Figure 17

The formula to get D<sub>op</sub> for a Type 4 ESPE is the following:

 $D_{op}$  (m) = 0.3 for operating distance < 3 m  $D_{op}$  (m) = operating distance (m) x tg  $2\alpha$  for operating distance  $\geq$  3 m

Installation precautions have to be taken to avoid interference between homologous devices. A typical situation is represented by the installation areas of several adjacent safety devices aligned one next to the other, for example in plants with different machines.

Figure 18 provides some examples for a 4 beam device; obviously a contemporary activation of more emitters is not possible and the emitter/receiver couples are activated sequentially.



#### 3.2.4. Active and passive orientation

The two units shall be assembled parallel each other, and looking at the references on the aluminium profile.

The configurations shown in Figure 19 must be avoided:

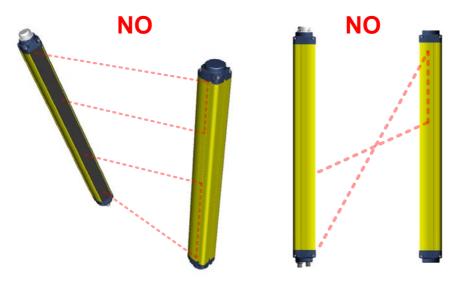


Figure 19

#### 3.2.5. Precautions to respect during the use of deviating mirrors

The operator must observe the following precautions when using the deviating mirrors:



- The alignment of the active unit can become a very critical operation when deviating mirrors are used. Even a very small angular displacement of the mirror is enough to loose alignment. The SG-LP laser pointer accessory can be used to avoid this problem.
  - The presence of dust or dirt on the reflecting surface of the mirror causes a drastic reduction in the range.

#### 3.2.6. Controls after first installation

• The control operations to carry-out after the first installation and before machine start-up are listed hereinafter. The controls must be carried-out by qualified personnel, either directly or under the strict supervision of the person in charge of machinery Safety.

#### Verify that:

• ESPE remains in SAFE state ( ) intercepting the beams along the protected area using the specific test piece (TP-40, TP-50, TP-90), following the Figure 20 scheme.

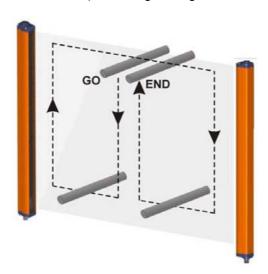


Figure 20

• ESPE has to be correctly aligned, press slightly on the product side in both directions the red LED 

- The activation of the TEST function causes the opening of the OSSD outputs (red LED on and controlled machine stop).
- The response time at machine STOP, including the ESPE and machine response times, must be included in the limits defined in the calculation of the safety distance (refer to section 3 "INSTALLATION MODE").
- The safety distance between the dangerous parts and ESPE must comply with the requirements indicated in section 3 "INSTALLATION MODE".
- A person must not access or remain between ESPE and the dangerous parts of the machine.
- Access to the dangerous areas of the machine must not be possible from any unprotected area.
- ESPE must not be disturbed by external light sources, ensuring that it remains in NORMAL OPERATION condition for at least 10-15 minutes and, placing the specific test piece in the protected area, in the SAFE state for the same period.
- Verify the correspondence of all the accessory functions, activating them in the different operating conditions.

#### 4. MECHANICAL MOUNTING

The active and passive units must be installed with the relevant sensitive surfaces facing each other and the distance must be included within the operating range of the model used (see section 13).

The two units must be positioned the most aligned and parallel possible. The next step is the fine alignment, as shown in section 7 – "ALIGNMENT PROCEDURE".



SG BODY series light curtains are provided without mounting brackets. It is possible to order separately the accessory kits of brackets described in the following paragraphs depending on the fastening mode required by the particular application. Please refer to section 14 – "ACCESSORIES".

#### 4.1. Side fixing brackets

As all the Datalogic Automation SG series safety light curtains, the most common way to fix the product is by taking advantage from the two grooves along the sides of the aluminium case, the 90° bracket system is made by ST-5090 + IM-5018 and screws (see Figure 21).

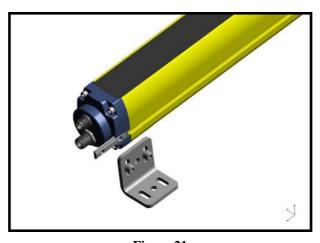


Figure 21

The ST-5090 is a 4 mm thickness sheet metal. The IM-5018 is a double nut M5 tapped obtained by machine tooling (for further details and recommended mounting positions see also paragraph 14.1).

#### 4.2. Rotating brackets

The rotative fixing has been improved and revised due to the size of the caps. Is possible indeed to ensure a 360° rotation around the dedicated cylindrical surfaces designed on the caps themselves. To obtain this is necessary to use the ST-5089, 4 mm thickness sheet metal with a special, dedicated shape. The screw to fix this bracket is the same one used to fix the closing caps, with an M4 nut (see Figure 22). For further informations refer to paragraph 14.2.

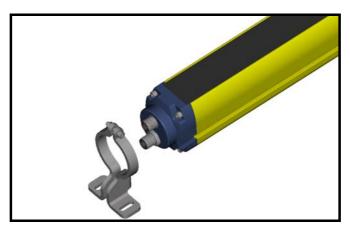


Figure 22

#### 4.3. Bottom fixing brackets

With the SG BODY series has been implemented a new kind of bracket fixing, by using the third groove, on the bottom side of the housing, that allows to use whether the 90° bracket ST-5090 or the new ST-5093 and, in both the cases, the same IM-5018 and screws seen before.

This kind of fixing is also very versatile in order to assembly the product into the new Protective Stands mechanical armor.

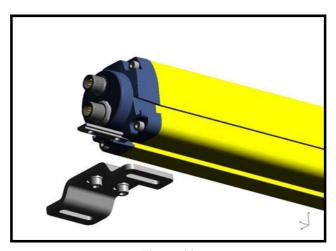
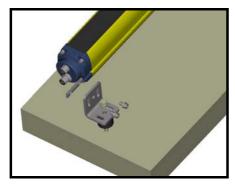


Figure 23

The ST-5093 is a 4 mm thickness sheet metal as well. For further details and recommended mounting positions see also paragraph 14.3.

#### 4.4. Vibration dampers

In case of applications with particularly strong vibrations, vibration dampers together with mounting brackets are recommended to reduce the impact of the vibrations (see Figure 24)



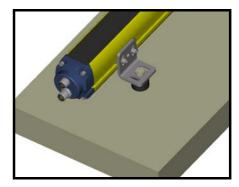


Figure 24

#### Mechanical muting arms mounting

SG BODY light curtains linear models are not provided as "L" or "T" models. These models must be built from linear models applying Muting arms accessories. Single sensor and reflector arms (RRX versions) are available as accessories and must be combined with the kit of mounting brackets for SG BODY light curtains. (refer to section 14 – "ACCESSORIES").

To mount the Muting arms on both the "L" and "T" version, use the fixing bracket shown in Figure 25.

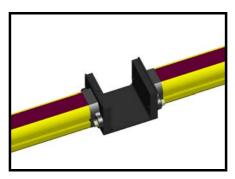


Figure 25

This accessory quarantees the perfect alignment of the arms and the perpendicularity respect to the main unit. Position the bracket on the main unit, after having mounted the arm or arms, as shown in Figure 26.

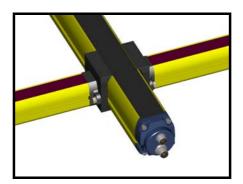
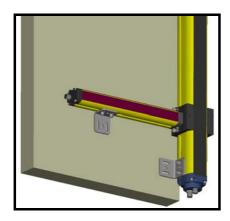


Figure 26

Verify the correct functioning position and block the group using the two plates and the screws and tightening them with a CH.2.5 allen key.

- In the "L" version mount the arms in order to intercept the object before entering in the light curtain sensitive area.
- The two arms have to be mounted in order to be the most parallel and aligned possible. The sensors have default alignment, but the rotation around the main arm can be further adjusted by regulating the specific fixing bracket.
- In critical applications due to the presence of strong vibrations, the arms have to be fixed using the specific fixing brackets (Figure 27).
- The Muting arms can be adjusted vertically according to the application and to the connecting cable lengths (typical range is 14 cm).

In presence of strong vibrations fixing brackets (see paragraph 4.1) for the Muting arms mounting are compulsory (Figure 27), which are optional in normal working conditions.



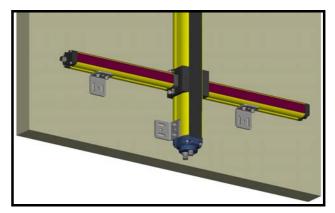


Figure 27

#### **4.5.1.** *Mechanical arm mounting (retro-reflex)*



The following aspects have to be considered during the mechanical arm mounting for the "L" and "T" light curtain models:

- Mount the arm with the active Muting sensors on the active unit and the arms with the reflectors on the passive unit.
- The use of retro-reflex arms for the Muting function limits the maximum operating distance to 3 meters.

#### 5. ELECTRICAL CONNECTIONS AND CONFIGURATION

All electrical connections to the emitting and receiving units are made through male M12 connectors, located on the lower part of the two units.

For active unit a M12 12-poles and a M12 5-poles connectors are used.

A closing cap coupled with the top cap of the RX unit can be unscrewed to access dip-switches slot. By means of internal dip-switches the user can set-up some functions, as described in paragraph 5.4.

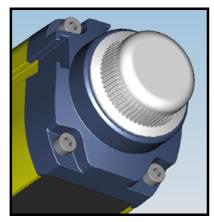




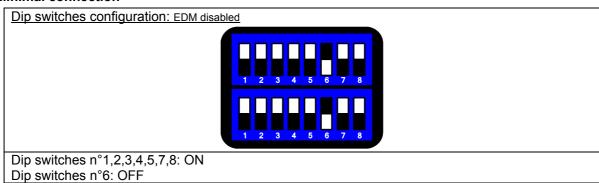
Figure 28

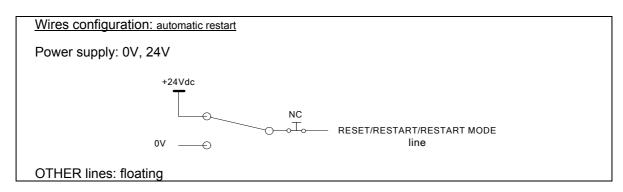
#### 5.1. Important notes for installation

For the correct functioning of the SG BODY series safety light curtains, the following precautions regarding the electrical connections have to be respected:

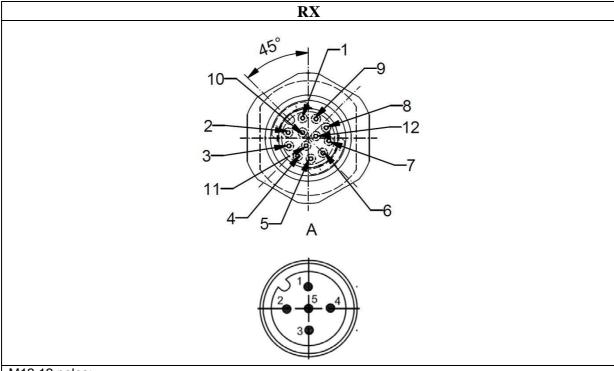
- Do not place connection cables in contact with or near high-voltage cables and/or cable undergoing high current variations (e.g. motor power supplies, inverters, etc.);
- Do not connect in the same multi-pole cable the OSSD wires of different light curtains;
- The device is already equipped with internal overvoltage and overcurrent suppression devices. The use of other external components is not recommended.

#### 5.2. Minimal connection





#### 5.3. Complete connection list



#### M12 12 poles:

- 1. 24V (brown)
- 2. 0V (blue)
- 3. RESET/RESTART/ RESTART MODE (white)
- 4. OVERRIDE1 (green)
- 5. OSSD2 (pink)
- 6. EDM (yellow)
- 7. MUTING ENABLE (black)
- 8. OSSD1 (grey)
- 9. OVERRIDE2 (red)
- 10. LAMP INPUT (violet)
- 11. OVERRIDE STATUS (grey-pink)
- 12. EARTH (red-blue)

#### M12 5 poles:

- 1. 24V (brown)
- 2. MUTING2 (white)
- 3. 0V (blue)
- 4. MUTING1 (black)
- 5. N.C. (grey)

#### 5.4. Complete dip-switches configuration

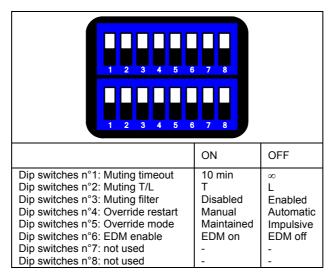


The device does not accept configuration changes during normal functioning. A change is accepted only beginning from the successive powering of the device. Particular attention has to be taken during the configuration dip-switch management and use.



Muting time-out " $\infty$ " does not comply with the requirements of IEC 61496-1. Therefore all possible risks must be considered and related precautions undertaken before selecting the " $\infty$ "option.

Note: For RX side the top and bottom dip-switches must be configured in the same manner. The "ON" position is the default.



#### 5.5. Restart mode and Reset/Restart button connection

The Restart mode and Reset/Restart wire must be connected through a N.C. button to the 0V or 24V from the power supply of the ESPE to select, respectively, manual restart or automatic restart.

The Reset/Restart wire can be used to enter alignment function, when N.C. button is pressed at start-up.



The RESET/RESTART button must be located in such a way that the operator can check the protected area during any reset operation (see section ).

#### 5.6. External relays connection

Example: connection to the safety relay.

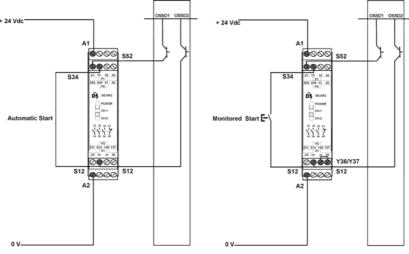


Figure 29

The previous figure shows the connection between the safety light curtains and the safety relay of the SE-SR2 series functioning in the Automatic Restart mode (left side) and Manual Restart with monitoring (right side).

- Do not use varistors, RC circuits or LEDs in parallel at relay inputs or in series at OSSD outputs.
- The OSSD1 and OSSD2 safety contacts cannot be connected in series or in parallel, but must be used separately (Figure 30), conforming to the plant's safety requirements.
- If one of these configurations is erroneously used, the device enters into the output failure condition (see section Errore. L'origine riferimento non è stata trovata. "Errore. L'origine riferimento non è stata trovata.").

• Connect both OSSDs to the activating device. Failure to connect an OSSD to the activating device jeopardises the system safety degree that the light curtain has to control.

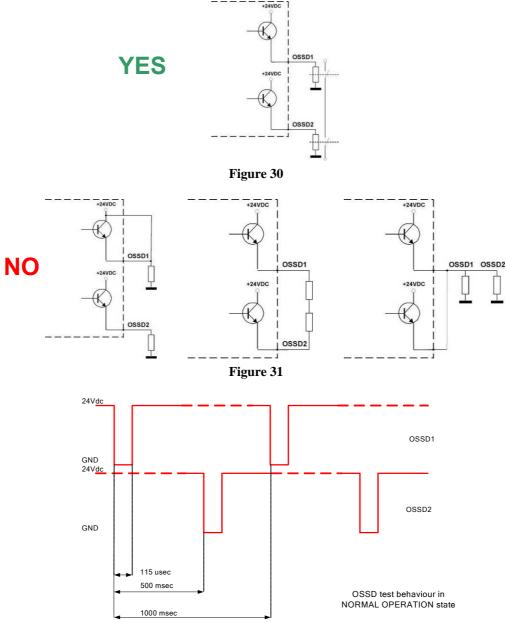


Figure 32

#### 5.7. EDM control connection

The EDM wire has to be connected to a 24 Vdc normally closed contact, before powering. The monitoring function, if selected, is not activated if at powering the wire is not correctly connected; in this case the light curtain enters in a failure condition.

#### 5.8. MUTING ENABLE input connection

The MUTING ENABLE wire must be connected to 0V or 24V from the power supply of the ESPE, respectively, to enable or to disable Muting function. Floating line level is the same as 0V.

#### 5.9. Muting arms or Muting function inputs connection

Muting arms or external Muting sensors can be connected to ESPE by mean of the committed M12 connector. Read see par. 6.5 – "Muting function" for the use and the positioning of the activating sensors.

#### 5.10. Override connection

The Override1 wire must be connected through a N.O. button to the 24 Vdc from the power supply of the ESPE; Override 2 wire must be connected through a N.O. button to the 0V from the power supply of the ESPE. If the wires are not correctly connected, the light curtain enters in a failure condition.



The OVERRIDE button/key must be located in such a way that the operator can check the protected area during any test.

#### 5.11. Earth connection

The SG BODY safety light curtain has to be connected as a protective class III equipment (SELV/PELV power supply), like in the table.

Electrical protection	layout connection	note
class III	SELV/PELV	

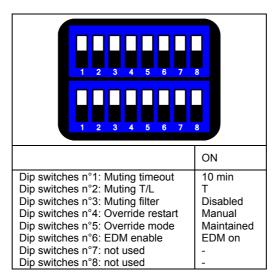
A functional earth is available on a line of the M12 connector on TX and RX equipment. User can optionally connect or leave floating the functional earth in order to achieve in own application a best compliance with electromagnetic Interferences.

#### 6. FUNCTIONING MODE

#### 6.1. Standard configuration

Line	Layout connection	Behaviour
RESET/RESTART/ RESTART MODE	+24Vdc NC O————IN line	Automatic restart
RESET/RESTART/ RESTART MODE	0V ——○ NC NN line	Manual restart
EDM	OSSD_1 OND	(EDM ENABLE: active)
MUTING ENABLE	0V or floating ——O—— MUTING ENABLE	Muting enabled
OVERRIDE STATUS	External control ——O—OVERRIDE STATUS	
MUTING1	MUTING SENSOR/ARM OUTPUT ————————— MUTING 1	
MUTING2	MUTING SENSOR/ARM OUTPUT ———————— MUTING 2	
OVERRIDE1	+24Vdc NO T OVERRIDE1	
OVERRIDE2	0V ——○——○——OVERRIDE2	
OSSDs	OSSDs OV	
LAMP INPUT	LAMP 24V	

The following table shows factory default configuration for dip-switches.

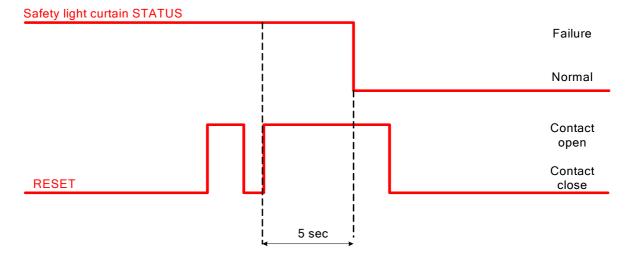


#### 6.2. Reset function

The RX light curtain has a RESET function that is activated consequently to an internal failure. The operator has to press the NC RESET button that resetting the break condition and thus the ESPE can return to a normal functioning behaviour.

The button has to be kept pressed for at least 5 seconds in one of the following conditions:

- Output failure;
- Optic failure;
- EDM test function failure;
- Lamp failure;



If the error is not removed, the light curtain goes in the failure configuration (for all failures) yet.

Notes: the micro controller failure is a non-restorable failure. In this case is necessary a "turn OFF-turn ON action" to return to a normal behavior. This is also valid for the following failures:

- Restart selection failure
- Override connection failure
- Override sequence failure
- Dip switch failure

#### 6.3. Restart mode selection function

The interruption of a beam due to an opaque object causes the opening of OSSD outputs and the stop of the safety light curtain, SAFE condition

ESPE standard operation can be reset to NORMAL OPERATION condition (OSSD safety contact closing condition, ) in two different ways:

<u>Automatic Restart:</u> after activation, ESPE resets to NORMAL OPERATION condition once the object has been removed from the controlled area.

<u>Manual Restart:</u> after activation, ESPE resets to NORMAL OPERATION condition only once the Restart function has been enabled and provided that the object has been removed from the controlled area (see Figure 33). This condition, called interlock, is signalled on the display (see paragraph 8.2 – "Diagnostic messages").



WARNING: Carefully assess risk conditions and restart modes.

In applications protecting access to dangerous areas, the automatic restart mode is potentially unsafe if it allows the operator to pass completely beyond the sensitive area. In this case, the manual restart or, for example, the manual restart of the SE-SR2 relay (paragraph 5.6 – "External relays connection") is necessary.

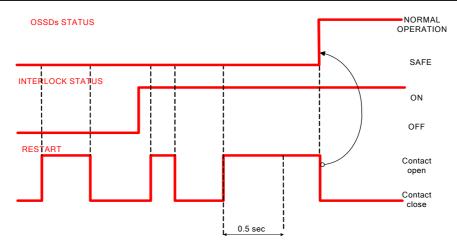


Figure 33 – Time chart for manual restart

Select either automatic or manual restart by connecting pin of RX connector (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

#### 6.4. EDM function

The light curtain has a function for monitoring actuation external devices (EDM). This function can be enabled or deactivated by dip-switches of RX device (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

#### EDM deactivated:

Disconnect or connect to 0V EDM input pin of RX connector.

#### EDM enabled:

Connect EDM input pin of RX connector (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION") to a 24 VDC normally closed contacts of the device to be monitored (see Figure 34).

**NOTE:** The decimal dot on the display shows that the function is enabled.

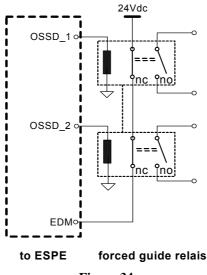
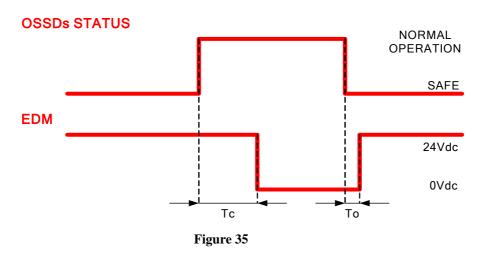


Figure 34

The function controls the NC contact switching according to the changes of the OSSD status. The timing diagram below explains the relationship between the cause (OSSDs) and the effect (EDM), with the maximum permissible delay.



- $T_c \ge 350$  msec time after the OSSD OFF-ON passage when EDM is carried-out;
- $T_0 \ge 100$  msec time after the OSSD ON-OFF passage when EDM is carried-out.

(two different times for the mechanical contact driven by a spring).

#### 6.5. Muting function

This function can be enabled or deactivated by pin of RX connector (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

The Muting sensors must be able to recognise the passing material (pallets, vehicles, ...) according to the material's length and speed. In case of different transport speeds in the Muting area, it is necessary to consider their effect on the total Muting duration.

• The Muting function, excludes the light curtain during functioning, maintaining active the OSSD outputs, according to particular operating requirements (Figure 36).

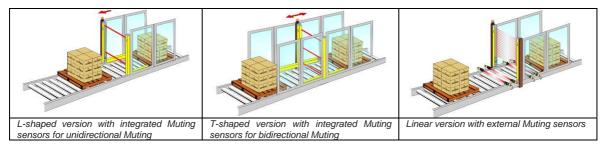


Figure 36

- •
- The safety light curtain is equipped with two inputs (Muting1 and Muting2) for the activation of this function, according to the Standards in force.
- This function is particularly suitable when an object, but not a person, has to pass through the dangerous area, under certain conditions.
- It is important to remember that the Muting function represents a forced system condition and therefore has to be use with the necessary precautions.
- If Muting1 and Muting 2 inputs are activated by two Muting sensors or actuators, these should be correctly connected and positioned in order to avoid undesired Muting or potentially dangerous conditions for the operator.
- State of Muting is signalled by Muting Lamp integrated on the top of receiver side (see Figure 37). When the MUTING function in ON the LAMP becomes active. Contextually also LAMP output line (PIN 10 M12-12 poles) is driven..



Figure 37

- During the installation take care to place the lamps in an as visible as possible position.
- If both the internal lamp and the external lamp are broken and/or not connected, the Muting request causes the opening of the safety contacts, the device is blocked in SAFE state and the failure is signalled (see par. 8.2 "Diagnostic messages").

a) b) c)

e)

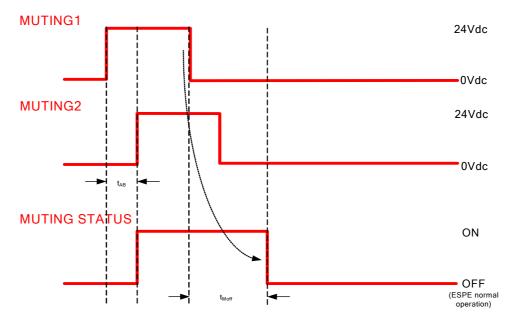
• Next picture shows an example of Muting functioning:

# 6.5.1. Muting T/L selection function

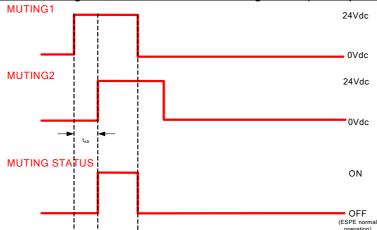
This function let the user select the requested configuration for muting sensors, and can be set by dipswitches of RX device (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

f)

<u>Temporal diagram of the Muting function for two-sensor configuration ( "L-shaped" or crossed-beam</u> versions)



As shown in the previous picture, tAB indicates the interval of time between MUTING1 and MUTING2 activation (see paragraph 6.5.4 - "Installation mode of Muting sensors"). After a tMoff interval of time between deactivation of MUTING1, light curtain exits the muting status and returns in normal operation (see paragraph 6.5.4 - "Installation mode of Muting sensors").



Temporal diagram of the Muting function for four-sensor configuration ("T-shaped" version)

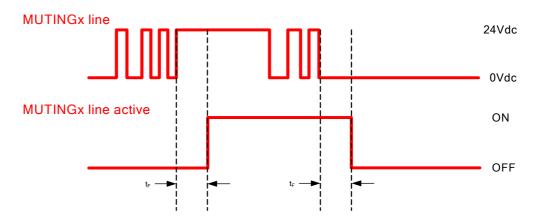
As shown in the previous picture, tAB indicates the interval of time between MUTING1 and MUTING2 activation (see paragraph 6.5.4 - "Installation mode of Muting sensors"). In this case, when MUTING1 de-activates, light curtain exits the muting status and returns in normal operation.

#### 6.5.2. Muting timeout selection function

This function let the user choose the muting timeout value between 10 minutes and infinite and can be set by dip-switches of RX device (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

#### 6.5.3. Muting low-pass filter function

The muting filter is a filter on the muting inputs; low-high or high-low transitions of MUTINGs signals are considered valid only if maintained for tF seconds ( $tF \ge 0.1$  s), as shown in the following figure.



This function can be enabled using dip-switches of RX device (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

#### 6.5.4. Installation mode of Muting sensors



Select carefully the configuration, as a wrong configuration can cause the incorrect functioning of the Muting function and a reduction of the safety level.



The Muting sensors must be positioned in such a way that the activation of the Muting function is not possible with the accidental passing of a person.

The Muting request can be performed activating the Muting1 first and then the Muting2, or viceversa. In this case, the second activation should occur within 4 sec. after the first; otherwise the Muting will not be activated.

Any Muting request can not be made if the ESPE is in the SAFE condition (red LED is ON and the beams are interrupted).

Figure 38 provides an installation example of a linear **SAFE***asy*<sup>TM</sup> light curtain mounted on a conveyor, with the relative external Muting sensors.

The A1, A2, B1, B2 Muting activation sensors temporarily inhibit the ESPE if a package passes between the sensors.

The outputs of these sensors are connected to the Muting1 and Muting2 inputs of the receiving unit of the ESPE.

The contacts of these sensors are controlled by the receiving unit.

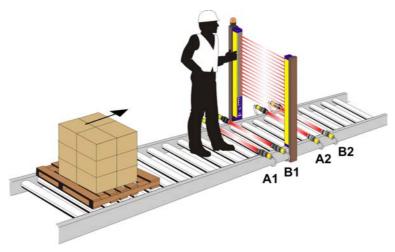


Figure 38

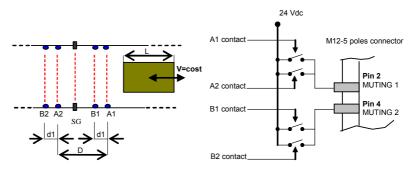
Optoelectronic, mechanical, proximity sensors etc, can be used as Muting sensors, with closed contact in the presence of the object to be detected.

The following are some configuration examples when using the Muting function.

#### Application with 4 optoelectronic sensors: parallel-beam configuration

The solution is suitable for applications requiring bidirectional movements of objects. For correct functioning, position the dip-switches to select "T" configuration.

#### Muting sensors connection:



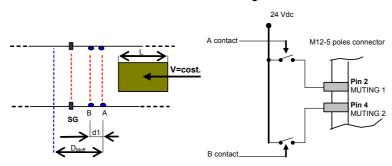
Symbol	Unit	Formula	Min	Тур	Max	Description
D	cm		L			Interaxis between sensors connected to the same Muting input
$\mathbf{D}_1$	cm	= V * t <sub>AB</sub> * 100	0.1			Interaxis between sensor A and sensor B
t <sub>AB</sub>	sec	Compulsory condition	0.01		4	Activation time of the second sensor after first sensor activation (A→B) (B→A)
DoA	cm		$d_1 + D$			Distance to respect between adjacent objects to obtain the correct Muting functioning
L	cm		D			Object dimension to activate the Muting function passing between the sensors
V	cm/sec	$= d_1 / t_{AB}$			250 (suggested)	Object speed to activate the Muting function passing between the sensors

## Application with 2 optoelectronic sensors: parallel-beam configuration

The solution is suitable for applications requiring unidirectional movements of objects. For correct functioning, position the dip-switches to select "L" configuration.

The reset of normal Muting functioning is obtained at a DMoff distance from sensor A.

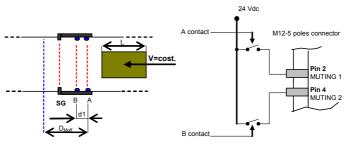
#### Muting sensors connection:



Symbol	Unit	Formula	Min	Тур	Max	Description
$\mathbf{D}_1$	cm	= V * t <sub>AB</sub> * 100	0.1			Interaxis between sensor A and sensor B
$\mathbf{D}_{ ext{Moff}}$	cm	Compulsory condition		33		Distance from sensor A at which the Muting function is deactivated and the light curtain returns to normal functioning
t <sub>AB</sub>	sec	Compulsory condition	0.01		4	Activation time of the second sensor after first sensor activation (A→B)
$t_{ m Moff}$	sec	$= D_{Moff}/V$	0.132 (at max. suggested speed)		8	Time period, referred to sensor A, after which the Muting function is deactivated and the light curtain returns to normal functioning
D <sub>OA</sub>	cm	$=$ $D_{Moff}$	49,5			Distance to respect between adjacent objects to obtain the correct Muting functioning
L	cm		d <sub>1</sub>			Object dimension to activate the Muting function passing between the sensors
v	cm/sec	$= d_1 / t_{AB}$	4.125		250 (suggested)	Object speed to activate the Muting function passing between the sensors

## Application with L arm

### Muting sensors connector:



The L-configured solution with integrated Muting facilitates sensor installation and suits applications with unidirectional object passage.

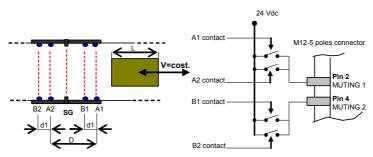
For correct functioning, position the dip-switches to select "L" configuration.

The reset of normal Muting functioning is obtained at a DMoff distance from sensor A.

Symbol	Unit	Formula	Min	Тур	Max	Description
$\mathbf{d_1}$	cm	Compulsory condition		16.5		Interaxis between sensor A and sensor B
$\mathbf{D}_{ ext{Moff}}$	cm	Compulsory condition		33		Distance from sensor A at which the Muting function is deactivated and the light curtain returns to normal functioning
t <sub>AB</sub>	sec	Compulsory condition	0.01		4	Activation time of the second sensor after first sensor activation $(A \rightarrow B)$
$t_{ m Moff}$	sec	$= D_{Moff}/V$	0.132 (at max. uggested speed)		8	Time period, referred to sensor A after which the Muting function is deactivated and the light curtain returns to normal functioning
D <sub>OA</sub>	cm	$= D_{Moff}$	49,5			Distance to respect between adjacent objects to obtain the correct Muting functioning
L	cm		$d_1$			Object dimension to activate the Muting function passing between the sensors
v	cm/sec	$=d_1/t_{AB}$	4.125		250 (suggested)	Object speed to activate the Muting function passing between the sensors

# Application with T arm

#### Muting sensors connection:



The T-configured solution with integrated Muting facilitates sensor installation and suits applications with bidirectional object passage.

For correct functioning, position the dip-switches to select "T" configuration.

The reset of normal Muting functioning is obtained at the deactivation of the A2 sensor (or B1 according to the object passage direction).

Symbol	Unit	Formula	Min	Тур	Max	Description
D	cm	Compulsory condition		34.5		Interaxis between sensors connected to the same Muting input
$\mathbf{d_1}$	cm	Compulsory condition		16.5		Interaxis between sensor A and sensor B
t <sub>AB</sub>	sec	Compulsory condition	0.01		4	Activation time of the second sensor after first sensor activation (A1 $\rightarrow$ B1) (B2 $\rightarrow$ A2)
$t_{ m Moff}$	sec	= D/V	0.132 (at max. suggested speed)		8	Time period, referred to sensor A2(B1), after which the Muting function is deactivated and the light curtain returns to normal functioning
D <sub>OA</sub>	cm		$d_1 + D = 51$			Distance to respect between adjacent objects to obtain the correct Muting functioning
L	cm	= D	34.5			Object dimension to activate the Muting function passing between the sensors
v	cm/sec	$=d_1/t_{AB}$	4.125		250 (suggested)	Object speed to activate the Muting function passing between the sensors

#### 6.6. Override function

This function allows to force a Muting condition when machine reset is necessary, even if one or more beams are interrupted by passing material.

The purpose is to clear the protected area of any material accumulated consequently to a failure in the working cycle.

For example, if a pallet stops in front of the protected area, the conveyor may not restart as the ESPE (that has one or more interrupted beams) opens the OSSD outputs and will not permit the controlled area clearance.

The activation of the Override function makes permits this operation.

#### 6.6.1. Activation of the Override function

- Override function cannot be activated when the light curtain is in SAFE state or NORMAL OPERATION state, but only when OVERRIDE condition is met. OVERRIDE condition is met when the light curtain is in SAFE state and one MUTING beam is obscured.
- When the requirements for the activation are met, a signalling is provided onto the LED display in order to inform users that an override is possible and required (see Figure 39).



Figure 39

Two input lines are provided for the activation of the override function, Override1 and Override2, that must be connected to +24 Vdc and to 0 Vdc respectively by means of two normal open contacts (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION").

Standard requires the use of spring return hold-to-run devices or secure momentary action push buttons, located so that it will not possible to enter the hazardous zone whilst maintaining the action on devices.

Override function can be actuated closing both contacts: whatever contact can be activated first.

The maximum out-of-sync interval time allowed is 400 ms, while the minimum one is 0 ms, as shown in the timing diagram of Figure 41.

While override is actuated, the integrated lamp will be blinking.

State of Override is signalled by the Override Lamp integrated on the top of receiver side (see Figure 40). When the Override function is ON the LAMP output signal is driven.



Figure 40

During the installation take care to place the lamps in an as visible as possible position.

If both the internal lamp and the external lamp are broken and/or not connected, the Override request causes the opening of the safety contacts, the device is blocked in SAFE state and the failure is signalled (see par. 8.2 - "Diagnostic messages").

Override function will automatically terminate when one of the following condition will be given:

- all the muting sensors are de-actuated (\*);
- the pre-determined time limit has expired;
- the requirements for actuation are not met any more (at least one override input line is deactivated).
  - (\*) This is true for light curtains configured as T Muting. For light curtains configured as L Muting, override will terminate when muting sensors are de-actuated AND the light curtain's beams are free.

- Keep the button pressed until the clearance of the protected area has been completed.
- The maximum length of the Override function is 120 sec. After that time, the ESPE returns to NORMAL OPERATION, even if the OVERRIDE button is pressed. Obviously, if the button is released within the 120 seconds, the Override function stops immediately.
- When override is de-actuated, the light curtain will return into the NORMAL OPERATION.

All possible fault conditions at runtime are shown below.

Fault	Cause	Action
Contacts out-of-sync: when trying to actuate the override function, the activation timer expires .	A shortcut to VDC or GND may be present on one of the override input lines or a contact may be defective.	Override is not actuated: the fault is signalled by the user interface (see Figure 42) This is not a lockout condition: the override can be run after fixing the fault.

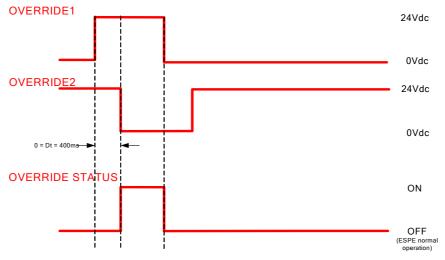


Figure 41 - Temporal diagram of the Override function

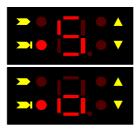


Figure 42 - Override sequence failure

#### 6.6.2. Override input mode function

This function let the user choose, setting dip-switches of RX device (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION"), the input mode for override lines, and in particular select impulsive Override mode.

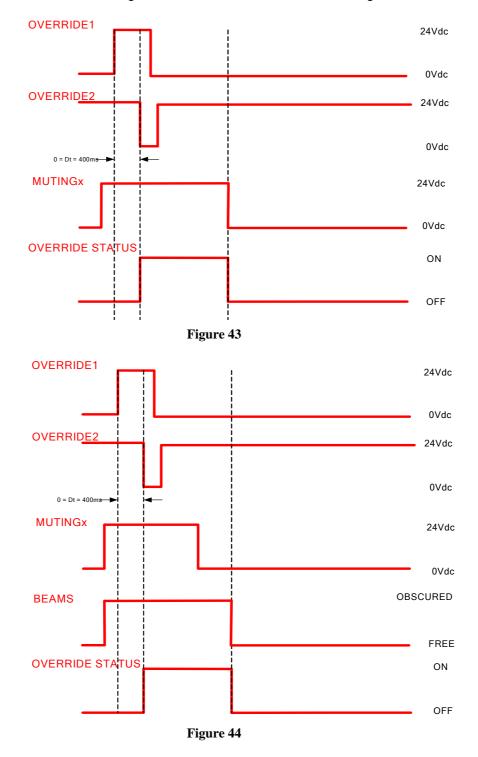
The Edge Triggered Override function forecasts that the Override state rests even if the related activation buttons are released. The device exits the Override state when one of the following event happens:

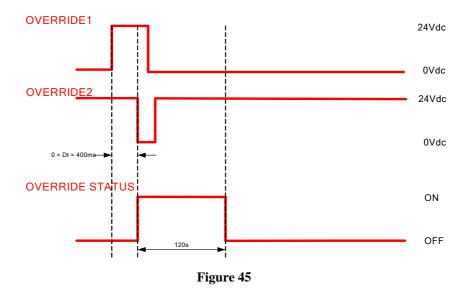
- the muting sensors are free (T-Muting, Figure 43), or the muting sensor are deactivated and the beams of the light curtain are free (L-Muting, Figure 44).
- The time-out expires (Figure 45).

For this reasons, all possible risks must be considered and related precautions undertaken. Recommends that:

- all control operations must be assigned only to a well trained and skilled personnel;
- the user assigned to the actuation of the override function, must be able to work in a condition of maximum surveillance and visibility of the whole area.

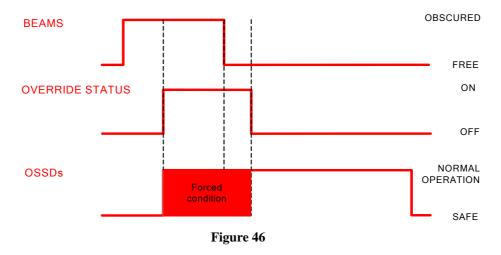
When Override status ends, the light curtain returns to standard functioning.





#### 6.6.3. Override restart mode function

This function let the user choose, setting dip-switches of RX device (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION"), the restart mode after Override when ESPE is configured in manual restart mode, and in particular to force automatic restart mode of light curtain as shown in Figure 46.



Override with automatic restart function, allows to restart automatically the normal working of the curtain (normal operation condition) when the detection area (curtains + sensors) is cleared.

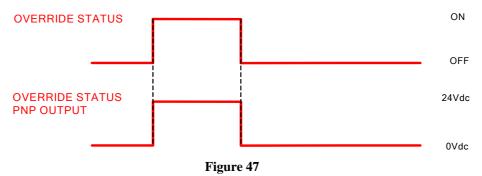
This function does not comply with the requirements of IEC 61496-1, because is a forcing of the safety condition.

For this reasons, all possible risks must be considered and related precautions undertaken. Recommends that:

- all control operations must be assigned only to a well trained and skilled personnel;
- the user assigned to the actuation of the override function, must be able to work in a condition of maximum surveillance and visibility of the whole area.

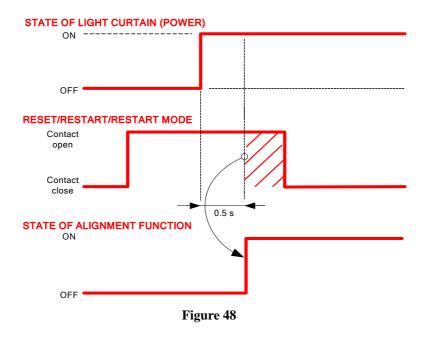
#### 6.6.4. Override status

When the device enters the Override status, OVERRIDE STATUS PNP output line provided on M12 12 RX connector (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION") switches from 0Vdc to 24Vdc, providing electronic information to the user.



## 6.7. Alignment function

SG BODY series light curtains are fitted with a system which informs the user about reached alignment degree. The ALIGNMENT function also can be activated by simply pressing the external normally closed push-button link to RESET/RESTART/RESTART MODE line (see section 5 – "ELECTRICAL CONNECTIONS AND CONFIGURATION") for at least 0.5 sec at start-up, as shown in the timing diagram of Figure 48.



When a good state of alignment is reached a power OFF and a power ON operation carry back the ESPE in normal operation (OSSDs in ON state). In the alignment mode the OSSDs are OFF.

## 7. ALIGNMENT PROCEDURE

The good alignment between the active and the passive unit of the ESPE is necessary to obtain the correct behaviour of the light curtain. A good alignment avoid a not steady light curtain status (OSSDs flicker on→off and vice versa) due to dust or vibration.

The alignment is perfect if the optic axes of the active unit's beams coincide with the optic axes of the corresponding mirrors on the passive unit.

It is important to define the means of symbol drawn on optic side of light curtain.

The direction of arrows associated to the two yellow led are correlated to the first and the last emitter/receiver couple, referring the position of M12 connector. Signals are clearly identified through symbols allowing their immediate reading, independent of bars directions; a short description of LEDs signals proves nevertheless necessary so as to avoid misunderstandings.



Figure 49

Figure 50 shows that the first couple emitter/receiver is the nearest to M12 connector; the last couple emitter/receiver is the farest to M12 connector.

The standard installation described hereinafter is the one shown in Figure 50 for a SG4-RB4 model, i.e. with the bar assembled with the connectors pointing down. In SG4-RB2 models, obviously, the first and the last couple coincide.

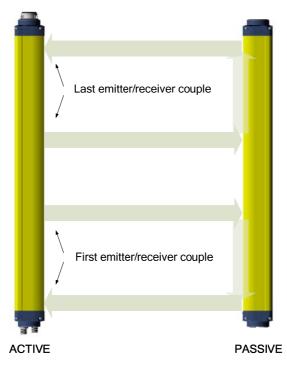


Figure 50

An one digit display can inform the user about the level of alignment of the array of beams. In alignment mode the internal and external lamps blink as quickly as more the alignment level increases.

As operating distance increase, the SG-LP laser pointer tool attached on active or passive unit can be used to help the user to obtain the best alignment (see Figure 51).



Figure 51

Also for Muting arms installation similar considerations must be taken. In the following paragraphs the alignment procedure for light curtain and Muting arms are described.

### 7.1. Light curtain alignment procedure

The light curtain alignment can be effected only after having completed the mechanical installation and the electrical connections as described above. Compare alignment results with those given in the following table.

To enter alignment mode see paragraph 0 – "Alignment function".



ATTENTION: in alignment mode the OSSDs of the light curtain are in OFF state

Visualization	Alignment state	Alignment quality	OSSD state out of alignment-function
	First and last couple are not aligned	Bad	OFF
	Last couple isn't aligned	Bad	OFF
	First couple isn't aligned	Bad	OFF
> •	Every couple over the lower threshold and no couple over the upper threshold	Good	ON
	Every couple over the lower threshold and one couple over the upper threshold		ON
	Every couple over the upper threshold	Excerent	ON

1. Keep the active unit in a steady position and set the passive unit until the yellow LED (▼ FIRST) is OFF. This condition shows the alignment of the first emitter/receiver couple.

2. Rotate the passive unit, pivoting on the lower optics axis, until the yellow LED (▲ LAST) is OFF

NOTE: Ensure that the green LED ( NORMAL OPERATION) is steady ON.

- 3. Delimit the area in which the green LED ( ) is steady through some micro adjustments for the first and then for the second unit so to have the maximum alignment (3) and then place both units in the centre of this area.
- 4. Fix the two units firmly using brackets. Verify that the green LED () on the active unit is ON and beams are not interrupted, then verify that the red LED SAFE () turns ON if even one single beam is interrupted (condition where an object has been detected). This verification shall be made with the special cylindrical "Test Piece" having a size suitable to the resolution of the device used (refer paragraph 3.2.6 "Controls after first installation").
- 5. Switch OFF and ON the device in normal operating mode.

The alignment level is monitored also during device normal operating mode, and is visualized by a bar graph shown on the user interface. Once the curtain has been aligned and correctly fastened, the display signal is useful to check the alignment and to view any change in the environmental conditions (presence of dust, light disturbance and so on). The behavior is resumed in the next table.

Visualization	Alignment state	Alignment quality
	Every couple over the lower threshold and no couple over the upper threshold	Min
	Every couple over the lower threshold and one couple over the upper threshold	
	Every couple over the upper threshold	Excellent

#### 7.2. Correct muting arm alignment procedure

Once effected the safety light curtain alignment and the mechanical arm mounting and the relative connection, ensure the correct alignment of the arm sensors regulating the fixing bracket.

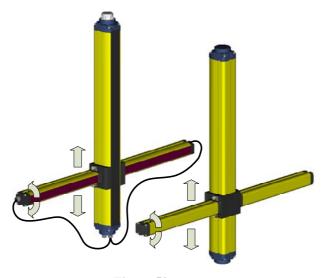


Figure 52

The arm position can be modified vertically and horizontally respect to the main axis. Avoid unsafe alignment conditions; carefully check the status of the red warning LEDs on active arms sensors. The alignment is perfect if all the warning LEDs are off.

## 8. DIAGNOSTICS

#### 8.1. User interface

A user interface aids the customer to control and check the state of the light curtain, for alignment mode, normal operation and for troubleshooting activity. User interface is composed by four LEDs and an one-digit display on the active unit.



Figure 53

## 8.2. Diagnostic messages

#### 8.2.1. Active unit side

The table completely explains all the visualization informations exept those relative to the alignment function (see par. 7.1 – "Light curtain alignment procedure").

Visualization	Status	Description	Action
> 0	INTERLOCK	Free beams, OSSDs OFF	User can take device in normal operation activating restart line.
INTERLOCK		Interrupted beams, OSSDs OFF	User must free beams path before activating restart line.
<b>&gt;</b> • • • • • • • • • • • • • • • • • • •	NORMAL OPERATION	OSSDs ON	
> 0	SAFE	OSSDs OFF	
<b>→</b>	NORMAL OPERATION, SAFE, INTERLOCK	EDM function active	
<b>→</b>	NORMAL OPERATION, SAFE, INTERLOCK	EDM function not active	
> 0	SAFE, INTERLOCK	Override function ready to be activated	User can activate Override function activating the correct sequence on Override lines.
	FAILURE LOCKOUT (recoverable)	Failure on one or both OSSDs, OSSDs OFF	User must activate RESET line. If ESPE does not reset user must contact Datalogic Automation Technical Support.

	FAILURE LOCKOUT (not recoverable)	Microcontroller failure, OSSDs OFF	User must turn OFF/ON ESPE. If the problem persists user must contact Datalogic Automation Technical Support.
	FAILURE LOCKOUT (recoverable)	Optical failure, OSSDs OFF	User must activate RESET line. If ESPE does not reset user must contact Datalogic Automation Technical Support.
	FAILURE LOCKOUT (recoverable)	EDM failure, OSSDs OFF	User must check EDM ENABLE line or dip-switches, EDM line, external switching device and activate RESET line. If ESPE does not reset user must contact Datalogic Automation Technical Support.
	FAILURE LOCKOUT (not recoverable)	Override connection failure, OSSDs OFF	User must check Override lines connection and turn OFF/ON ESPE. If the problem persists user must contact Datalogic Automation Technical Support.
	SAFE	Override sequence failure, OSSDs OFF	User must check Override lines activation sequence timings and repeat Override sequence. If the problem persists user must contact Datalogic Automation Technical Support.
	FAILURE LOCKOUT (not recoverable)	Dip switch failure, OSSDs OFF	User must check dip-switch configuration and turn OFF/ON ESPE. If the problem persists user must contact Datalogic Automation Technical Support.
	FAILURE LOCKOUT (recoverable)	Internal and external lamp failure, OSSDs OFF	User must check LAMP INPUT line and activate RESET line. If ESPE does not reset user must contact Datalogic Automation Technical Support.
> 0	ESPE OFF	Power supply failure, OSSDs OFF	User must check power supply connection. If the problem persists user must contact Datalogic Automation Technical Support.

## 9. PERIODICAL MAINTENANCE AND WARRANTY

The following is a list of recommended check and maintenance operations that should be periodically carried-out by qualified personnel (see also paragraph 3.2.6 – "Controls after first installation")

Check that:

- The ESPE stays in SAFE state ( ) during beam interruption along the entire protected area, using the specific Test Piece (TP-40, TP-50. TP-90), according to the Figure 20 scheme.
- The ESPE is correctly aligned. Press slightly product side, in both directions and the red LED ( must not turn ON.
- Enabling the TEST function, the OSSD outputs should open (the red LED ) is ON and the controlled machine stops).
- The response time upon machine STOP (including response time of the ESPE and of the machine) is within the limits defined for the calculation of the safety distance (see section 3 "INSTALLATION MODE").
- The safety distance between the dangerous areas and the ESPE are in accordance with the instructions included in section 3 "INSTALLATION MODE".
- Access of a person between ESPE and machine dangerous parts is not possible nor is it possible for him/her to stay there.
- Access to the dangerous area of the machine from any unprotected area is not possible.
- The ESPE and the external electrical connections are not damaged.

The frequency of checks depends on the particular application and on the operating conditions of the safety light curtain.

## 9.1. General information and useful data

Safety MUST be a part of our conscience.

The safety devices fulfil their safety function only if they are correctly installed, in accordance with the Standards in force. If you are not certain to have the expertise necessary to install the device in the correct way, Datalogic Automation Technical Support is at your disposal to carry out the installation.

The device uses fuses that are not self-resetting. Consequently, in presence of short-circuits causing the cut-off of these fuses, both units shall be sent to Datalogic Automation Technical Support department.

A power failure caused by interferences may cause the temporary opening of the outputs, but the safe functioning of the light curtain will not be compromised.

### 9.2. Warranty

Datalogic Automation guarantees each brand new SG BODY system, under standard use conditions, against manufacturing defects in material and workmanship for a period of 36 (thirty-six) months from the date of manufacturing.

Datalogic Automation will not be liable for any damages to persons and things caused by wrong installation modes or device use.

Warranty validity is subject to the following conditions:

- User shall notify Datalogic Automation the failure within thirty-six months from product manufacturing date.
- Failure or malfunction shall not have been originated directly or indirectly by:
- use for unsuitable purposes:
- failure to comply with the intended use prescriptions;
- negligence, unskillfulness, wrong maintenance;
- repairing, changes, adaptations not made by Datalogic Automation personnel, tampering with the device, etc.:
- accidents or crashes (even due to transportation or by force majeure causes);
- other causes not depending from Datalogic Automation

If the device does not work, send both units (receiver and emitter) to Datalogic Automation.

The Customer is responsible for all transport charges and damage risks or material loss during transport, unless otherwise agreed.

All replaced products and parts become a property of Datalogic Automation.

Datalogic Automation does not accept any warranty or right other than the above-described ones. No requests for compensation for expenses, activities stop or other factors or circumstances somehow connected to the failure of the product or one of its parts to operate cannot be put forward for any reason.

In case of problems, please contact Datalogic Automation Service Department.

#### **Service Department**

**Phone no.:** +39 051 6765611 **Fax no.:** +39 051 6759324

## 10. DEVICE MAINTENANCE

SG BODY safety light curtains do not require special maintenance operations.

To avoid the reduction of the operating distance, optic protective front surfaces must be cleaned at regular intervals.

Use soft cotton cloths damped in water.

Do not apply too much pressure on the surface in order to avoid making it opaque.

Please do not use on plastic surfaces or on light curtain painted surfaces:

- · alcohol or solvents
- wool or synthetic cloths
- paper or other abrasive materials

#### 10.1. Product disposal

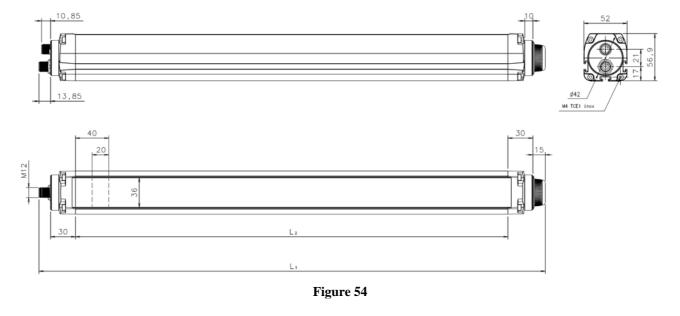
Under current Italian and European laws, Datalogic Automation is not obliged to take care of product disposal at the end of its life.

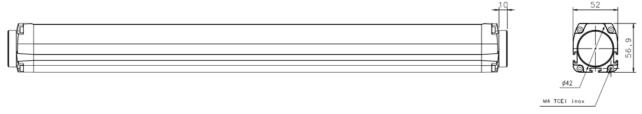
Datalogic Automation recommends to dispose of the product in compliance with local laws or contact authorised waste collection centres.

# 11. TECHNICAL DATA

TECHNICAL DATA	Floatical Data			
	Electrical Data			
Power supply:	24 Vdc ± 20%			
Active unit consumption (RX):	6.5 W max (without load)			
Outputs:	2 PNP outputs short-circuit protection (1.4 A @55°C)			
Output current:	0.5 A max / each output			
Output voltage - ON min:	Power supply value less 1 V			
Output voltage - OFF max:	0.2 V			
Output capacitive load	2.2 uF @24Vdc			
Response time:	From 11 to 24 ms See section 13 – "ORDER DATA"			
Protected height:	from 500 mm to1200 mm See section 13 – "ORDER DATA"			
Safety category:	Type 4 (ref. EN 61496-1)			
	SIL 3 (ref. EN 61508) SIL CL 3 (ref. EN 62061)			
	PL e Cat. 4 (ref. IEC 13849-1 2008)			
	See section 13 – "ORDER DATA"			
Auxiliary functions:	Reset, Restart selection, Alignment, EDM, Muting, Override			
Electrical protection – Layout connection:	class III – SELV/PELV			
Connections:	M40 5 40 mala			
	M12 5, 12 poles			
Cable length ( for power supply):	70 m. max			
Pollution degree	2			
- change a constant a	Optical Data			
Light source:	Infrared LED (950 nm wavelength )			
Resolution:	40 mm			
Nesolution.	319,75 mm			
	419.75 mm			
	519,75 mm			
Beam spacing	20 mm			
sam spasmg	300 mm			
	400 mm			
	500 mm			
Operating distance:	From 0,5 to 8 mt (see section 13 – "ORDER DATA")			
Ambient light rejection:	IEC 61496-2			
Mechanic	cal and environmental data			
Operating temperature:	055°C			
Storage temperature:	-25+ 70 °C			
Temperature class:	T6			
Humidity:	1595 % (no condensation)			
Water protection grade:	IP 65 (EN 60529)			
I VIUIGUUUS	0.35 mm width 10 55 Hz frequency 20 sweep for each axis 1			
Vibrations:	0.35 mm width, 1055 Hz frequency, 20 sweep for each axis, 1 octave/min (EN 60068-2-6)			
Shock resistance:				
	octave/min (EN 60068-2-6)			
Shock resistance:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)			
Shock resistance: Housing material: Caps material:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)			
Shock resistance: Housing material: Caps material: Front glass material:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector			
Shock resistance: Housing material: Caps material: Front glass material:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,3 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,3 Kg SG4-RB3-080-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 2,1 Kg SG4-RB4-090-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,3 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RDB2 (passive): 1,2 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,3 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg SG4-RB4-090-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RBD2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2T-050-OO-W: 1,3 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 2,1 Kg SG4-RB4-090-OO-W: 2,6 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB3T-050-OO-W: 1,8 Kg SG4-RB3-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RDB2L (passive): 1,2 Kg SG4-RDB2L (passive): 1,2 Kg SG4-RDB3T (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg SG4-RDB3T (passive): 1,7 Kg SG4-RDB3T (passive): 1,7 Kg SG4-RDB3T (passive): 1,7 Kg			
Shock resistance: Housing material: Caps material: Front glass material: Connections:	octave/min (EN 60068-2-6)  16 ms (10g) 1.000 shock for each axis (EN 60068-2-29)  Painted aluminium (yellow RAL 1003)  PBT Valox 508 (pantone 072-CVC)  PMMA  M12 connector  SG4-RB2-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,3 Kg SG4-RB2L-050-OO-W: 1,8 Kg SG4-RB3L-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB3T-080-OO-W: 1,8 Kg SG4-RB4-090-OO-W: 2,1 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RB4-120-OO-W: 2,6 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,2 Kg SG4-RDB2 (passive): 1,7 Kg SG4-RDB3 (passive): 1,7 Kg			

# 12. DIMENSIONS





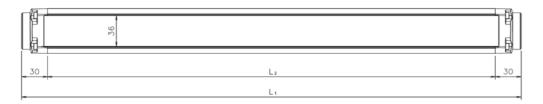


Figure 55

Model	L1 [mm]	L2 [mm]
SG4-RB2-050-OO-W (Figure 54)	609,35	520,5
SG4-RB2L-050-OO-W (Figure 54)	609,35	520,5
SG4-RB2T-050-OO-W (Figure 54)	609,35	520,5
SG4-RB3-080-OO-W (Figure 54)	909,35	820,5
SG4-RB3L-080-OO-W (Figure 54)	909,35	820,5
SG4-RB3T-080-OO-W (Figure 54)	909,35	820,5
SG4-RB4-090-OO-W (Figure 54)	1009,35	920,5
SG4-RB4-120-OO-W (Figure 54)	1309,35	1220,5
SG4-RDB2 (Figure 55)	580,5	520,5
SG4-RDB2L (Figure 55)	580,5	520,5
SG4-RDB2T (Figure 55)	580,5	520,5
SG4-RDB3 (Figure 55)	880,5	820,5
SG4-RDB3L (Figure 55)	880,5	820,5
SG4-RDB3T (Figure 55)	880,5	820,5
SG4-RDB4-090 (Figure 55)	980,5	920,5
SG4-RDB4-120 (Figure 55)	1280,5	1220,5

# 13. ORDER DATA

Description	Protecte d height (mm)	Beams (Nr.)	Resolution (mm)	Response time (msec)	Interaxis (mm)	Operating Distance (m)	Code
SG4-RB2-050-OO-W	500	2	519,75	11	500	0.58	957951030
SG4-RB2L-050-OO-W	500	2	519,75	11	500	0.53	957951060
SG4-RB2T-050-OO-W	500	2	519,75	11	500	0.53	957951080
SG4-RB3-080-OO-W	800	3	399,75	12	380	0.58	957951040
SG4-RB3L-080-OO-W	800	3	399,75	12	380	0.53	957951070
SG4-RB3T-080-OO-W	800	3	399,75	12	380	0.53	957951090
SG4-RB4-090-OO-W	900	4	319,75	12	300	0.56.5	957951180
SG4-RB4-120-OO-W	1200	4	419,75	12	400	0.58	957951050
SG4-RDB2 (passive)	500	2	-	-	500	-	957951100
SG4-RDB2L (passive)	500	2	-	-	500	-	957951130
SG4-RDB2T (passive)	500	2	-	-	500	-	957951150
SG4-RDB3 (passive)	800	3	-	-	380	-	957951110
SG4-RDB3L (passive)	800	3	-	-	380	-	957951140
SG4-RDB3T (passive)	800	3	-	-	380	-	957951160
SG4-RDB4-090 (passive)	900	4	-	-	300	-	957951170
SG4-RDB4-120 (passive)	1200	4	-	-	400	-	957951120

	EN ISO 13849-1	EN 954-1	EN IEC 61508	EN IEC 62061	Prob. of danger failure/hour	Life span	Mean Time to Dangerous Failure	Average Diagnostic Coverage	Safe Failure Fraction	Hardware Fault Tolerance
Description	PL	CAT	SIL	SIL CL	PFHd (1/h)	T1 (years)	MTTFd (years)	DC	SFF	HFT
SG4-RB2-050-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB2L-050-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB2T-050-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB3-080-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB3L-080-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB3T-080-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB4-090-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1
SG4-RB4-120-OO-W	е	4	3	3	8,57E-09	20	439	96,50%	97,50%	1

# 14. ACCESSORIES

# 14.1. Side fixing bracket

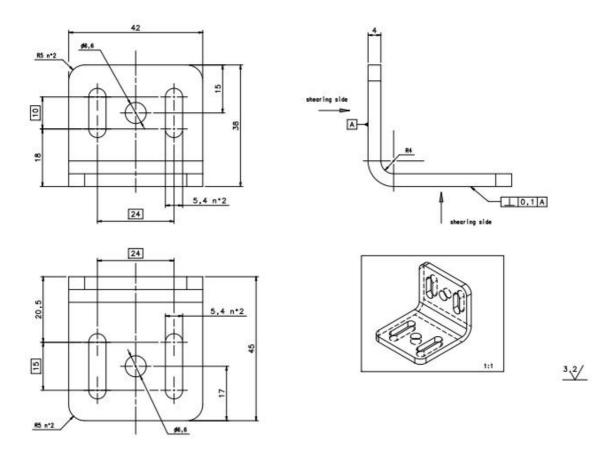
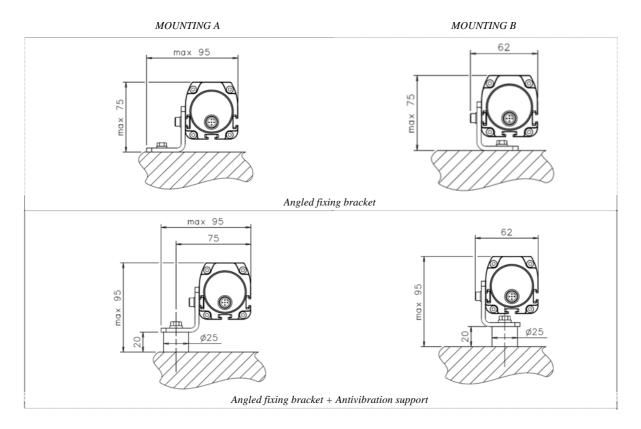


Figure 56

# 14.1.1. Side fixing bracket mounting



MODEL	DESCRIPTION	CODE
ST-K4STD-SG BODY BIG	Fixing brackets for angle mounting (4 pc kit)	95ASE1950
ST-K4AV	Antivibration support (4 pc kit)	95ACC1700
ST-K6AV	Antivibration support (6 pc kit)	95ACC1710

The recommended mounting positions according to the light curtain length are shown in Figure 57 and in the subsequent table.

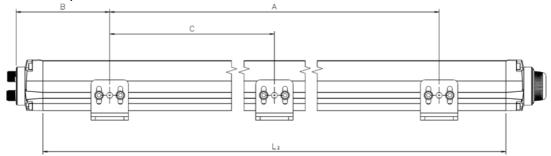
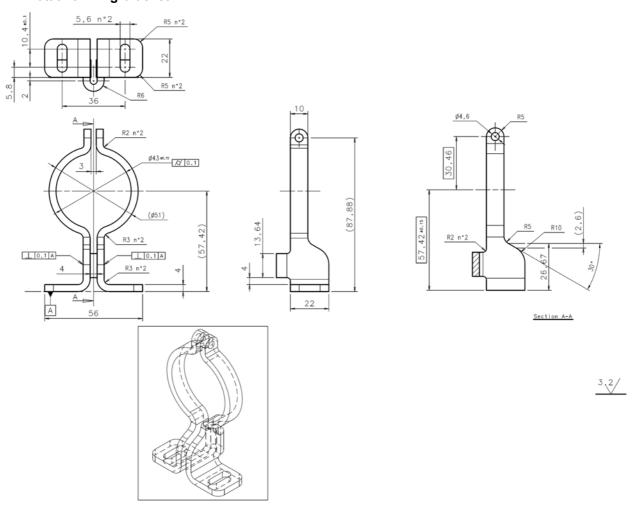


Figure 57

Description	L <sub>2</sub> [mm]	A [mm]	B [mm]	C [mm]	Code
SG4-RB2-050-OO-W	520,5	320,5	100	-	957951030
SG4-RB2L-050-OO-W	520,5	320,5	100	-	957951060
SG4-RB2T-050-OO-W	520,5	320,5	100	-	957951080
SG4-RB3-080-OO-W	820,5	370,5	125	-	957951040
SG4-RB3L-080-OO-W	820,5	370,5	125	-	957951070
SG4-RB3T-080-OO-W	820,5	370,5	125	-	957951090
SG4-RB4-090-OO-W	920,5	620,5	150	-	957951180
SG4-RB4-120-OO-W	1220,5	1020,5	100	510,25	957951050
SG4-RDB2 (passive)	520,5	320,5	100	-	957951100
SG4-RDB2L (passive)	520,5	320,5	100	-	957951130
SG4-RDB2T (passive)	520,5	320,5	100	-	957951150
SG4-RDB3 (passive)	820,5	370,5	125	-	957951110
SG4-RDB3L (passive)	820,5	370,5	125	-	957951140
SG4-RDB3T (passive)	820,5	370,5	125	-	957951160
SG4-RDB4-090 (passive)	920,5	620,5	150	-	957951170
SG4-RDB4-120 (passive)	1220,5	1020,5	100	510,25	957951120

# 14.2. Rotative fixing bracket



## 14.2.1. Rotative fixing bracket mounting

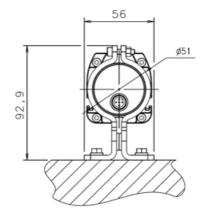
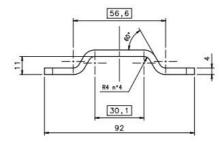
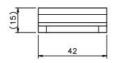


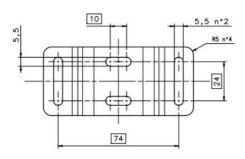
Figure 58

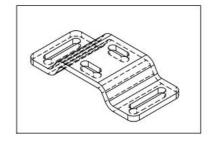
MODEL	DESCRIPTION	Code	
ST-K4ROT-SG BODY BIG	Rotative fixing bracket mounting (4 pc kit)	95ASE1960	i

# 14.3. Bottom fixing bracket









3,2/

Figure 59

# 14.3.1. Bottom fixing bracket mounting

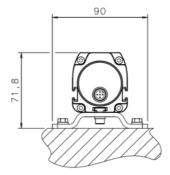
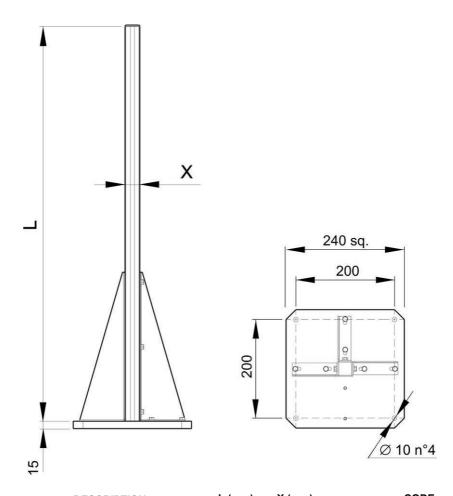


Figure 60

MODEL	DESCRIPTION	Code
ST-K4REAR-SG BODY BIG	Bottom fixing bracket mounting (4 pc kit)	95ASE1970

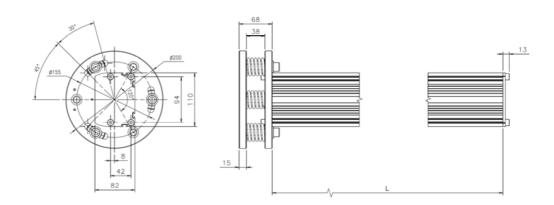
## 14.4. Column and floor stands

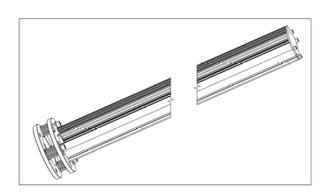


MODEL	DESCRIPTION	L (mm)	X (mm)	CODE
SE-S 800	Column and floor stand H= 800 mm	800	30x30	95ACC1730
SE-S 1000	Column and floor stand H= 1000 mm	1000	30x30	95ACC1740
SE-S 1200	Column and floor stand H= 1200 mm	1200	30x30	95ACC1750
SE-S 1500	Column and floor stand H= 1500 mm	1500	45x45	95ACC1760
SE-S 1800	Column and floor stand H= 1800 mm	1800	45x45	95ACC1770

## 14.5. Protective stands

SG BODY light curtains can be housed in protective stands, composed by SG-SB and SG-PS accessories.





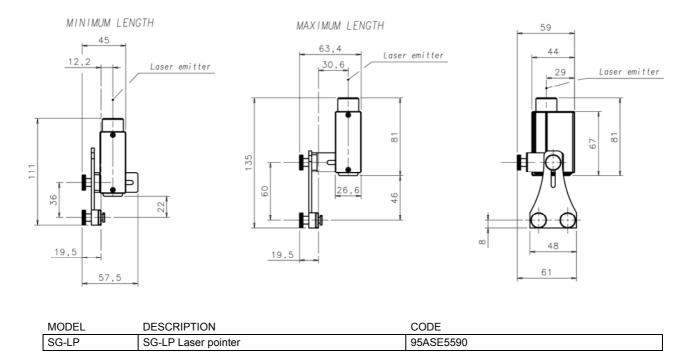
MODEL	CODE
SG-SB	95ASE1660

MODEL	DESCRIPTION	L (mm)	CODE
SG-PS 600	Protective stand H= 600 mm	600	95ASE1610
SG-PS 900	Protective stand H= 900 mm	900	95ASE1620
SG-PS 1200	Protective stand H= 1200 mm	1200	95ASE1630
SG-PS 1650	Protective stand H = 1650 mm	1650	95ASE1640
SG-PS 1900	Protective stand H = 1900 mm	1900	95ASE1650

## 14.6. Test Piece

MODEL	DESCRIPTION	CODE
TP-40	Test piece Ø 40 mm	95ASE1820
TP-50	Test piece Ø 50 mm	95ASE1790
TP-90	Test piece Ø 90 mm	95ASE1800

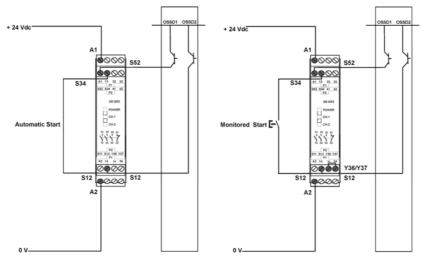
# 14.7. Laser pointer



## 14.8. Connection cables

MODEL	DESCRIPTION	CODE
CS-A1-03-U-03	5-pole M12 cable (axial) 3 m	95ASE1170
CS-A1-03-U-05	5-pole M12 cable (axial) 5 m	95ASE1180
CS-A1-03-U-10	5-pole M12 cable (axial) 10 m	95ASE1190
CS-A1-03-U-15	5-pole M12 cable (axial) 15 m	95ASE1200
CS-A1-03-U-25	5-pole M12 cable (axial) 25 m	95ASE1210
CS-A1-03-U-50	5-pole M12 cable (axial) 50m	95A252700
CS-A1-06-U-03	8-pole M12 cable (axial) 3 m	95ASE1220
CS-A1-06-U-05	8-pole M12 cable (axial) 5 m	95ASE1230
CS-A1-06-U-10	8-pole M12 cable (axial) 10 m	95ASE1240
CS-A1-06-U-15	8-pole M12 cable (axial) 15 m	95ASE1250
CS-A1-06-U-25	8-pole M12 cable (axial) 25 m	95ASE1260
CS-A1-06-U-50	8-pole M12 cable (axial) 50 m	95A252710
CS-A1-10-U-03	12-pole M12 cable (axial) 3 m	95A252720
CS-A1-10-U-05	12-pole M12 cable (axial) 5 m	95A252730
CS-A1-10-U-10	12-pole M12 cable (axial) 10 m	95A252740
CS-A1-10-U-15	12-pole M12 cable (axial) 15 m	95A252750
CS-A1-10-U-25	12-pole M12 cable (axial) 25 m	95A252760
CS-A1-10-U-50	12-pole M12 cable (axial) 50 m	95A252770

# 14.9. Safety relay SE-SR2



The drawing shows the connection between the safety light curtain and the Type 4 safety relay of the SE-SR2 series functioning in the automatic Start mode (left side) and manual Start with monitoring (right side).

MODEL	DESCRIPTION	CODE
SE-SR2	Type 4 safety relay - 3 NO 1NC	95ACC6170

#### 14.10. Muting Arms

T-shaped models are available with integrated Muting sensors for bidirectional Muting, L-shaped models for unidirectional Muting and linear models without integrated Muting sensors are available. By means of Muting arms accessories, linear models can be converted into T-shaped models and L-shaped models.

The following figures show the dimensions of active, emitter and receiver arms (Figure 61), passive arms (Figure 62) and the mounting bracket (Figure 63).

Note: If emitter/receiver arms are used instead of active/passive, power supply must be cabled to passive unit

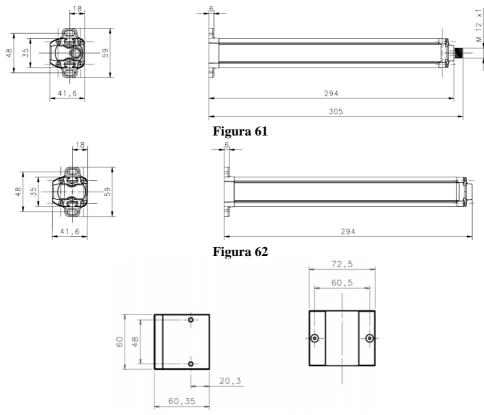


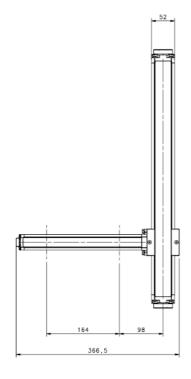
Figura 63

MODEL	DESCRIPTION	CODE
SG-AS-ARM	SINGLE ACTIVE ARM WITH RRX SENSORS V2	95ASE1841
SG-PR-ARM	SINGLE PASSIVE ARM WITH REFLECTORS V2	95ASE1851
SG-F1-G1-ARMS	BRACCI PROIETTORE/RICEVITORE F1-G1	95ASE1880
SG-F2-G2-ARMS	BRACCI PROIETTORE/RICEVITORE F2-G2	95ASE1890

MODEL	DESCRIPTION	CODE
SG-CB-B	MUTING ARMS MOUNTING BRACKET KIT	95ASE1920

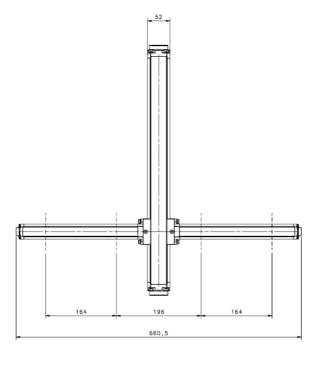
NOTE:To obtain a 'L' configuration with F/G arms use SG-F1-G1 ARM together with 2 pieces of SG-CB-B. Please install F1 arm on RX unit and G1 arm on TX in order to have them facing one to another. To obtain a 'T' configuration with F/G arms use SG-F1-G1 ARM and SG-F2-G2 ARMS together with 2 pieces of SG-CB-B. Please install F1 and F2 arms on RX unit and G1 and G2 arms on TX in order to have them facing one to another.

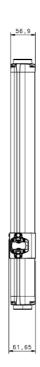
# SG BODY REFL. + ACTIVE/PASSIVE ARMS L





## SG BODY REFL.+ ACTIVE/PASSIVE ARMS T





#### 15. GLOSSARY

**ACTIVE OPTOELECTRONIC PROTECTIVE DEVICE (AOPD):** its detection function is achieved thanks to the use of optoelectronic receivers and emitters detecting the optical beams interruptions inside the device caused by an opaque object present inside the specified detecting area.

An active optoelectronic protective device (AOPD) can operate both in emitter-receiver mode and in retro-reflective light curtains.

**BLOCK CONDITION (=BREAK):** status of the light curtain taking place when a suitably-sized opaque object (see DETECTING CAPACITY) interrupts one or several light curtain beams.

Under these conditions, OSSD1 and OSS2 light curtain outputs are simultaneously switched OFF within the device response time.

BREAK: see "Block condition" in the glossary.

**CONTROLLED MACHINE:** machine having the potentially-dangerous points protected by the light curtain or by another safety system.

**CROSSING HAZARD:** situation under which an operator crossing the area controlled by the safety device and this latter stops and keeps the machine stopped until the hazard is eliminated, and then enters the dangerous area. Now the safety device could not be able to prevent or avoid an unexpected restart of the machine with the operator still present inside the dangerous area.

**DANGEROUS AREA:** area representing an immediate or imminent physical hazard for the operator working inside it or who could get in contact with it.

**DETECTING CAPACITY:** sensor function parameter limit as specified by the manufacturer, which activates the electrosensitive protection equipment (ESPE). In case of an active optoelectronic protective device (AOPD), with resolution we mean the minimum dimension, which an opaque object must have in order to interrupt at least one of the beams that constitute the sensitive area.

EDM: see "External device monitoring" in the glossary.

**ELECTROSENSITIVE PROTECTIVE EQUIPMENT (ESPE):** assembly of devices and/or components working together to activate the protective disabling function or to detect the presence of something and including at least: a sensor, command/control devices and output signal switching devices.

**EMITTER:** unit emitting infrared beams, consisting of a set of optically-synchronised LEDs. The emitting unit, combined with the receiving unit (installed in the opposite position), generates an optical "curtain", *i.e.* the detecting area.

**EXTERNAL DEVICE MONITORING (EDM):** device used by the ESPE to monitor the status of the external command devices.

**FINAL SWITCHING DEVICE (FSD):** part of the control system involving machine safety conditions. It breaks the circuit to the machine primary control element (MPCE) when the output signal switching device (OSSD) becomes inactive.

**FORCE-GUIDED CONTACTS:** Contacts can be guided forcibly when they are connected mechanically so that they can switch simultaneously, when the input stage is active.

If one contact of the series remains "hanged", no other relay contact is able to move.

This function allows the control of the EDM status.

**MACHINE OPERATOR:** qualified person allowed to use the machine.

**MACHINE PRIMARY CONTROL ELEMENT (MPCE):** electrically-powered element having the direct control of machine regular operation so as to be the last element, in order of time, to operate when the machine has to be enabled or blocked.

**MIN. INSTALLATION DISTANCE:** min. distance necessary to allow machine dangerous moving parts to completely stop before the operator can reach the nearest dangerous point. This distance shall be measured from the middle point of the detecting area to the nearest dangerous point. Factors affecting min. installation distance value are machine stop time, total safety system response time and light curtain resolution.

**N.O.:** normally opened **N.C.:** normally closed

**OFF STATUS:** status when the output circuit is interrupted and does not allow current stream.

ON STATUS: status when the output circuit is operational and allows current stream.

**OUTPUT SIGNAL SWITCHING DEVICE (OSSD):** part of the ESPE connected to machine control system. When the sensor is enabled during standard operating conditions, it switches to disabled status.

**PROTECTED AREA:** area where a specified test object is detected by the ESPE.

**PROTECTIVE DEVICE:** device having the function to protect the operator against possible risks of injury due to the contact with machine potentially-dangerous parts.

**QUALIFIED OPERATOR:** a person who holds a professional training certificate or having a wide knowledge and experience and who is acknowledged as qualified to install and/or use the product and to carry out periodical test procedures.

**RECEIVER:** unit receiving infrared beams, consisting of a set of optically-synchronised phototransistors. The receiving unit, combined with the emitting unit (installed in the opposite position), generates an optical "curtain", i.e. the detecting area.

**RESOLUTION:** see "Detecting capacity" in the glossary.

**RESPONSE TIME:** max. time elapsing between the occurrence of the event leading to sensor activation and the reaching of the inactive state by the output signal switching device (OSSD).

**RESTART:** see "Restart Interlocking Device" in the glossary.

**RESTART INTERLOCKING DEVICE:** device preventing machine automatic restart after sensor activation during a dangerous phase of machine operating cycle, after a change of machine operating mode, and after a variation in machine start control devices.

**RISK:** probability of occurrence of an injury and severity of the injury itself.

**SAFETY LIGHT CURTAIN:** it is an active optoelectronic protective device (AOPD) including an integrated system consisting of one or several emitting elements and one or several receiving elements forming a detection area with a detecting capacity specified by the supplier.

**START INTERLOCKING DEVICE (= START):** device preventing machine automatic start if the ESPE is live or the voltage is disabled and enabled once again.

**TEST PIECE:** opaque object having a suitable size and used to test safety light curtain correct operation.

**TYPE (OF ESPE):** the Electrosensitive Protective Equipment (ESPE) have different reactions in case of faults or under different environmental conditions. The classification and definition of the "type" (ex. type 2, type 4, according to IEC 61496-1) defines the minimum requirements needed for ESPE design, manufacturing and testing.

**WORKING POINT:** machine position where the material or semifinished product is worked.

