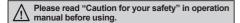
## Compact, amplifier built-in type with Universal voltage

## Features

- Small and power supply built-in type
- Easy installation with LED indicators on product
- Enables to set the operation mode by VR (Light ON/Dark ON)
- Status and output LED indication
- Built-in IC photo diode for ambient light and electrical noise







## Specifications

## • Free power, Relay contact output type

Model		BEN10M-TFR	BEN5M-MFR	BEN3M-PFR	BEN300-DFR	
Sensing	type	Through-beam	Retroreflective (Standard type)	Retroreflective (Built-in polarizing filter)	Diffuse reflective	
Sensing distance		10m	0.1 to 5m <sup>×1</sup>	0.1 to 3m <sup>×1</sup>	300mm <sup>×2</sup>	
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of Min. Ø60mm		Translucent, Opaque materials	
Hysteresis		_		Max. 20% at ratedsetting distance		
Response time		Max. 20ms				
Power supply		24-240VAC ±10% 50/60Hz, 24-240VDC ±10%(Ripple P-P: Max. 10%)				
Current of	consumption	Max. 4VA				
Light sou	rce	Infrared LED(850nm)		Red LED(660nm)	Infrared LED(940nm)	
Sensitivit	y adjustment	_	Adjustment VR			
Operation mode		Selectable Light ON or Dark ON by VR				
Control output		Relay contact output  Relay contact capacity: 30VDC 3A of resistive load, 250VAC 3A resistive load  Relay contact composition: 1c				
Relay life cycle		Mechanically: Min. 50,000,000 operation, Electrically: Min. 100,000 operation				
Light receiving element		Photo IC				
Indicator		Operation indicator: red, Stability indicator: green (The red lamp on Emitter of transmitted beam type is for power indication)				
Insulation resistance		Min. 20MΩ(at 500VDC megger)				
Insulation	n type	Double or strong insulation(Mark:  , Dielectric voltage between the measured input and the power: 1kV)				
Noise res	sistance	±1,000V the square wave noise(pulse width: 1μs) by the noise simulator				
Dielectric	strength	1000VAC 50/60Hz for 1minute				
Vibration	Mechanical	1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours				
Vibration	Malfunction	1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 10 minutes				
Shook	Mechanical	500m/s²(approx. 50G) in each of X, Y, Z directions for 3 times				
Shock Malfunction 100m/s²(approx. 10G) in each of X, Y, Z directions for 3 times		3 times				
F	Ambient illumination	Sunlight: Max. 11,0001x, Incandescent lamp: Max. 3,0001x (Receiver illumination)				
Environ- ment	Ambient temperature	-20 to 65°C, storage: -25 to 70°C				
Inche	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH				
Protection		IP50(IEC standard)				
Material		Case, Case cover: Heat resistant ABS    Sensing part: PC(with polarizing filter: PMMA)				
Cable		Ø5mm, 5-wire, Length: 2m(Emitter of through-beam type: Ø5mm, 2-wire, Length: 2m) (AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator out diameter: Ø1.25mm)				
A0000000	Individual		Reflector(MS-2)			
Accessory	Common	VR adjustment driver, Mounting bracket, Bolts/nuts				
Unit weight		Approx. 354g	Approx. 208g		Approx. 195g	
<b>※1</b> ⋅ The	sensing distance is s	specified with using the MS-	2 reflector and same as the	MS-4 reflector. Sensing dist	tance is setting range of the	

<sup>\*\*1:</sup> The sensing distance is specified with using the MS-2 reflector and same as the MS-4 reflector. Sensing distance is setting range of the reflector. The sensor can detect under 0.1m.

A-44 Autonics

When using reflective tapes, the reflection efficiency will vary by the size of the tape. Please refer to the "Reflection efficiency by reflective tape model" table before using the tapes.

X2: It is for Non-glossy white paper(100×100mm).

<sup>\*</sup>The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

# **Amplifier Built-in type with Universal voltage**

## • DC power, Solid state output type

Model		BEN10M-TDT	BEN5M-MDT	BEN3M-PDT	BEN300-DDT	Photo electric sensor
Sensing t	type	Through-beam	Retroreflective	Retroreflective (with polarizing filter)	Diffuse reflective	(B) Fiber
Sensing of	distance	10m	0.1 to 5m *1	0.1 to 3m *1	300mm **2	optic sensor
Sensing target		Opaque materials of Min. Ø16mm	Opaque materials of Min. Ø60mm		Translucent, Opaque materials	(C) Door/A
Hysteresis		_			Max. 20% at rated setting distance	sensor
Response	e time	Max. 1ms				(D) Proxim sensor
Power supply		12-24VDC ±10%(Ripple P-P: Max. 10%)				
Current c	onsumption	Max. 50mA				(E)
ight sou	rce	Infrared LED(850nm)		Red LED(660nm)	Infrared LED(940nm)	Pressu
Sensitivity	y adjustment	— Adjustment VR				361130
Operation	n mode	Selectable Light ON or Da	rk ON by VR			(F)
Control output		NPN open collector / PNP open collector simultaneous output  •Load voltage: Max. 30VDC •Load current: Max. 200mA •Residual voltage - NPN: Max. 1V, PNP: Max. 2.5V				Rotary encoder
rotection	n circuit	Reverse polarity protection, Short-circuit protection				
Light receiving element		Photo IC				
Indicator		Operation indicator: Red, Stability indicator: Green (The red lamp on Emitter of transmitted beam type is for power indication)				(H) Temp.
Insulation resistance		Min. 20MΩ(at 500VDC megger)				
Noise resistance		±240V the square wave noise(pulse width: 1µs) by the noise simulator				
Dielectric	strength	1000VAC 50/60Hz for 1minute				(I) SSR/
/ibration		1.5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 2 hours				Power
Shock		500m/s²(approx. 50G) in each of X, Y, Z directions for 3 times				
	Ambient illumination	Sunlight: Max. 11,0001x Incandescent lamp: Max. 3,0001x (Receiver illumination)			(J) Count	
Environ-	Ambient temperature	e -20 to 65°C, storage: -25 to 70°C				000000
nent	Ambient humidity	35 to 85%RH, storage: 35 to 85%RH				
rotection	n	IP50(IEC standard)				(K) Timer
Material		• Case, Case cover: Heat resistant ABS • Sensing part: PC(with polarizing filter: PMMA)				
Cable		Ø5mm, 4-wire, Length: 2m(Emitter of through-beam type: Ø5mm, 2-wire, Length: 2m)				(L) Panel
		(AWG22, Core diameter: 0.08mm, Number of cores: 60, Insulator diameter: Ø1.25mm)				Panel
Accessory Individual Common Approval			Reflector(MS-2)	<u> </u>		-
		VR adjustment driver, Mounting bracket, Bolts/nuts				(M) Tacho
		CE			Speed	
Unit weight		Approx. 342g	Approx. 200g		Approx. 187g	(AD)
	,			s the MS-4 reflector Sensing	distance is setting range of the	(N) Displa

<sup>※1:</sup> The sensing distance is specified with using the MS-2 reflector and same as the MS-4 reflector. Sensing distance is setting range of the reflector. The sensor can detect under 0.1m.
When using reflective tapes, the reflection efficiency will vary by the size of the tape. Please refer to the "Reflection efficiency by re-

When using reflective tapes, the reflection efficiency will vary by the size of the tape. Please refer to the "Reflection efficiency by reflective tape model" table before using the tapes.

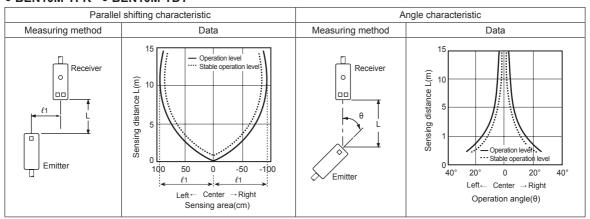
X2: It is for Non-glossy white paper(100×100mm)

\*The temperature or humidity mentioned in Environment indicates a non freezing or condensation environment.

## Feature data

## 

## • BEN10M-TFR • BEN10M-TDT



(O) Sensor controller

(P) Switching

mode powe supply

motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

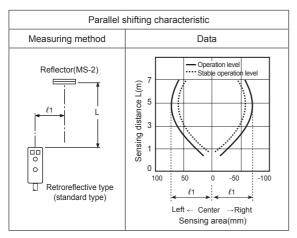
Autonics A-45

## **BEN Series**

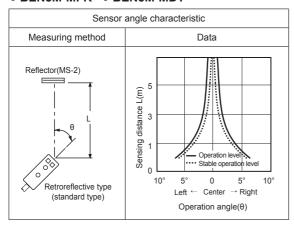
## Feature data

## **○** Retroreflective type(Standard type)

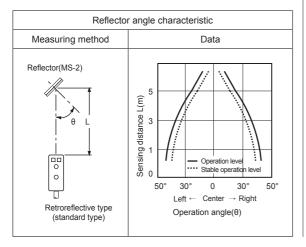
## • BEN5M-MFR • BEN5M-MDT



#### BEN5M-MFR BEN5M-MDT

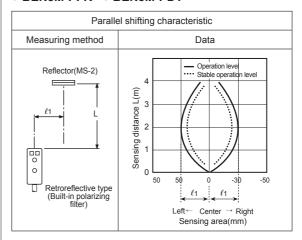


#### • BEN5M-MFR • BEN5M-MDT

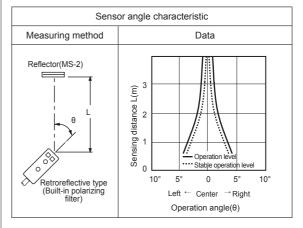


## **◎** Retroreflective type(Built-in polarizing filter)

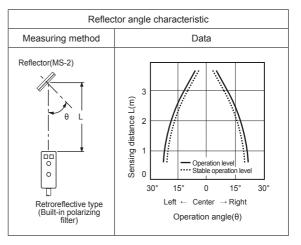
#### • BEN3M-PFR • BEN3M-PDT



#### BEN3M-PFR BEN3M-PDT



#### • BEN3M-PFR • BEN3M-PDT

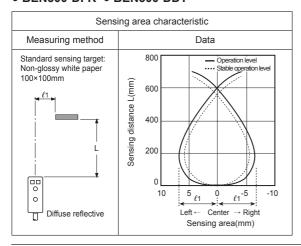


A-46 Autonics

# **Amplifier Built-in type with Universal voltage**

## O Diffuse reflective type

## BEN300-DFR ● BEN300-DDT



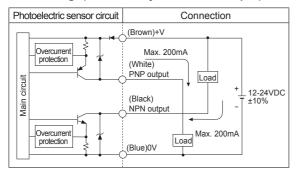
## Operation mode

Operation mode	Light ON		
Receiver operation	Received light Interrupted light		
Operation indicator (red LED)	ON OFF		
Transistor output	ON OFF		

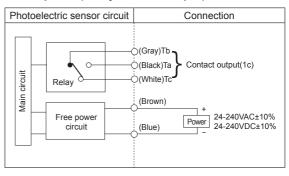
Operation mode	Dark ON		
Receiver operation	Received light Interrupted light		
Operation indicator (red LED)	ON OFF		
Transistor output	ON OFF		

## **■** Control output diagram

## • DC voltage(NPN/PNP synchronous output)

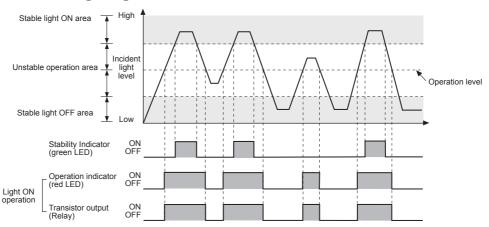


## Free power(Relay contact output)



\*In case of product with the output protection device, if terminals of control output are short circuited or overcurrent condition exists, the control output turns OFF due to protection circuit.

## Operation timing diagram



\*\*The waveforms of "Operation indicator" and "Transistor output" are for Light ON operation.
They are opposite operation for Dark ON operation.

Autonics A-47

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor (D) Proximity

(E) Pressure sensor

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp.

(I) SSR/ Power controller

(J)

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller (P) Switching

Switching mode power supply

Stepper motor& Driver&Controlle

(R) Graphic/ Logic panel

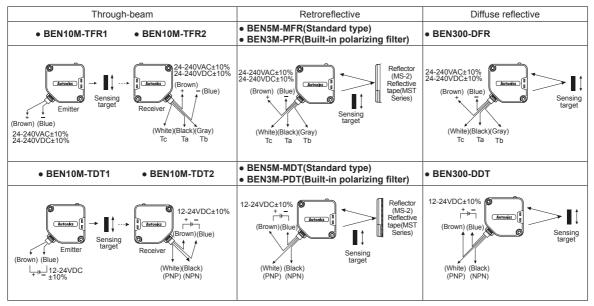
(S) Field network device

> (T) Software

(U) Othe

## **BEN Series**

## Connections



\* Unused line must be insulated.

## Dimensions

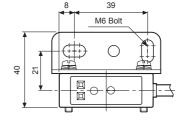
(unit: mm)

# Stability indicator Operation mode selection VR BEN300-DFR (€

Adjustment VR

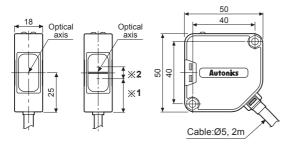
(Except for through-beam type)

## Connect the bracket

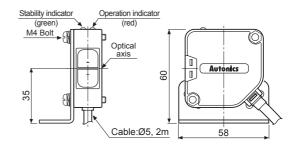


# •Through-beam •Retroreflective •Diffuse reflective

Operation indicato



X1: Retroreflective: 21.25mm, Diffuse reflective: 20.25mmX2: Retroreflective: 7.5mm, Diffuse reflective: 9.5mm



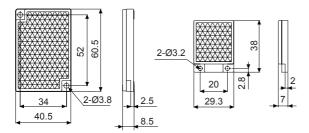
A-48 Autonics

## **Amplifier Built-in type with Universal voltage**

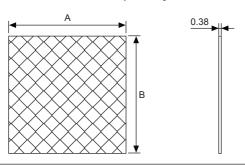
#### Reflector

· MS-2

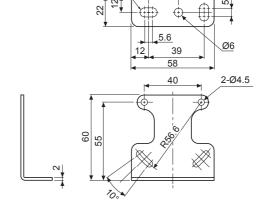
· MS-4(sold separately)



## • Reflective tape(sold separately)



#### Bracket



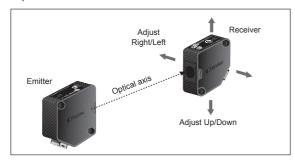
M6 Bolt

	A	В
MST-50-10	50	50
MST-100-5	100	100
MST-200-2	200	200

## ■ Mounting and sensitivity adjustment

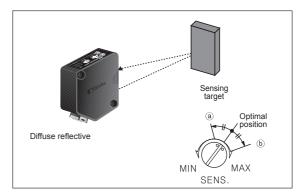
## Through-beam type

- Supply the power to the photoelectric sensor, after setting the emitter and the receiver facing each other.
- Set the receiver in center of position in the middle of the stability range of indicator adjusting the receiver or the emitter right and left, up and down.
- After adjustment, check the stability of operation putting the object at the optical axis.
- XIf the sensing target is translucent body or smaller than Ø16mm, it can be missed by sensor cause light penetrate it.



## O Diffuse reflective type

- The sensitivity should be adjusted depending on a sensing target or mounting place.
- Set the target at a position to be detected by the beam, then turn the adjustment VR until position (a) where the operation indicator turns ON from min. position of the adjustment VR.
- 4. Set the adjustment VR at the center of two switching position (a), (b).
- %The sensing distance indicated on specification chart is for 100×100mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.



(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor (D) Proximity

(F)

(E) Pressure sensor

> (F) Rotary encoder

Connector/ Socket

Temp. controller

> (I) SSR/ Power controller

Counter

imer

Panel neter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

> O) ensor ontroller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controller

(R) Graphic/ Logic panel

(S) Field network device

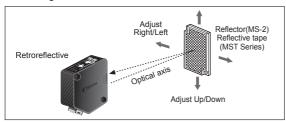
(T) Software

(U) Other

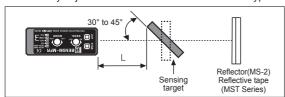
Autonics A-49

## Retroreflective type

- Supply the power to the photoelectric sensor, after setting the photoelectric sensor and the reflector or reflective tape in face to face.
- Set the photoelectric sensor in the position which indicator turns on, as adjusting the reflector or the sensor right and left, up and down.
- 3. Fix both units tightly after checking that the unit detects the target.



- If using more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when the target is near to photoelectric sensor. Therefore put enough space between the target and the photoelectric sensor or the surface of the target should be installed at angle of 30° to 45° against optical axis. (When a sensing target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)
- X Sensitivity adjustment: Refer to the diffuse reflective type's.

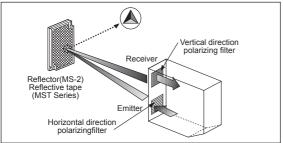


- XIf the mounting place is too narrow, please use MS-4 instead of MS-2.



## Retroreflective type with polarizing filter

The light passed through the polarizing filter of the emitter reaches to the MS-2 reflector or reflective tape converting as horizontal direction. It reaches to the receiver element of polarizing filter converting as vertical by the MS-2 reflector or reflective tape. Therefore, this type can also detect reflective mirror.



# Reflective efficiency by reflective tape model

	Retroreflective type (Standard)	Retroreflective type (Built-in polarizing filter)
MST-50-10 (50×50mm)	110%	110%
MST-100-5 (100×100mm)	160%	130%
MST-200-2 (200×200mm)	180%	180%

※Reflective efficiency may vary depending on usage environment and installation conditions.

The sensing distance and minimum sensing target size increase as the size of the tape increases.

Please check the reflection efficiency before using reflective tapes.

※For using reflective tape, installation distance should be min. 20mm.

A-50 Autonics